

Spring 2008 - 6.002

Pset #8 Solutions

①

### Exercise 8.1

$$i_{IN}(t) = 1 \text{ mA } u(t)$$

$$v_{IN}(t) = 1 \text{ V } (1 + e^{-t/1\mu\text{s}}) u(t)$$

$$v_{IN}(0) = 2 \text{ V}$$

@  $t=0^+$  all the current is going through the resistor,  $R_1$ .

$$R_1 = \frac{2 \text{ V}}{1 \text{ mA}} = 2 \text{ k}\Omega$$

$$v_{IN}(\infty) = 1 \text{ V}$$

@  $t \rightarrow \infty$  the inductor is a short and  $R_1$  &  $R_2$  are in parallel

$$\frac{R_1 R_2}{R_1 + R_2} = \frac{1 \text{ V}}{1 \text{ mA}} = 1 \text{ k}\Omega$$

$$R_2 = 2 \text{ k}\Omega$$

$$\tau = 1\mu\text{s} = \frac{L}{R_1 + R_2}$$

$$\Rightarrow L = (1\mu\text{s})(4 \text{ k}\Omega)$$

$$L = 4 \text{ mH}$$

### Exercise 8.2

@  $t=0^+$  the capacitor looks like a short.

$$v_{IN}(0^+) = \left(\frac{1}{2} \text{ k}\Omega\right)(1 \text{ mA}) = \frac{1}{2} \text{ V}$$

@  $t \rightarrow \infty$  the capacitor is an open

$$v_{IN}(\infty) = (1 \text{ k}\Omega)(1 \text{ mA}) = 1 \text{ V}$$

$$\tau = R_{\text{tot}} C = (2 \text{ k}\Omega)\left(\frac{1}{2} \mu\text{F}\right) = 1 \times 10^{-3} \text{ s}$$

$$v_{IN}(t) = \left[ \frac{1}{2} \text{ V} + \frac{1}{2} \text{ V} \left(1 - e^{-t/1.0 \times 10^{-3} \text{ s}}\right) \right] u(t)$$

Problem 8.1

(2)

(A)  $v(0^+) = v(0^-) = 0$   
 $i(0^+) = i(0^-) = 0$

No infinite current/voltage

$$i_c(t) = I = C \frac{dv(t)}{dt} \implies v(t) = \frac{1}{C} \int_{0^+}^t i_c(\tau) d\tau + \cancel{v(0^+)} \rightarrow 0$$

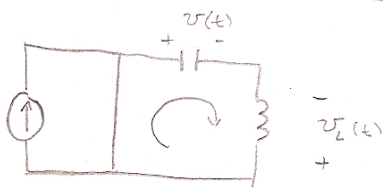
$$= \frac{I t}{C}$$

$v_L(t) = 0 \implies i(t) = k \implies i(t) = 0$   
 (constant)

$$v(t) = \frac{I \cdot t}{C}$$

$$i(t) = 0 \quad \text{for } 0 \leq t \leq T_1$$

(B)



KVL:  $v_L(t) = v(t) = L \frac{di}{dt}$

$$v(t) = L \frac{d}{dt} \left( -C \frac{dv(t)}{dt} \right)$$

$$LC \frac{d^2 v(t)}{dt^2} + v(t) = 0$$

$$\frac{d^2 v(t)}{dt^2} + \frac{1}{LC} v(t) = 0$$

Let  $\omega_0 = \frac{1}{\sqrt{LC}}$

Choose:  $v(t) = A \cos(\omega_0 t')$

$t' = t - T_1$

$v(T_1) = A = \frac{I T_1}{C}$

Plugging into part (a)

$$\therefore v(t) = \frac{I T_1}{c} \cos[\omega_0(t - T_1)], \quad T_1 \leq t \leq T_2$$

$$i(t) = -c \frac{dv(t)}{dt} = -c \left( -\frac{I T_1 \omega_0}{c} \right) \sin(\omega_0(t - T_1))$$

$$i(t) = I T_1 \omega_0 \sin[\omega_0(t - T_1)], \quad T_1 \leq t \leq T_2$$

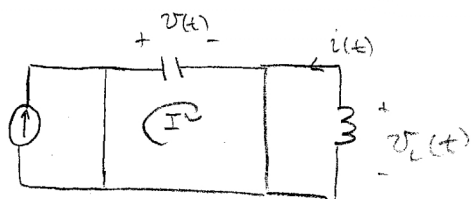
When  $v(t) = 0$ ,  $t = T_2$

$$\sin(\omega_0(T_2 - T_1)) = 0$$

$$\therefore \omega_0 [T_2 - T_1] = \frac{\pi}{2}$$

$$T_2 = T_1 + \frac{\pi}{2\omega_0}$$

(c)



$$v_L(t) = 0 \Rightarrow i(t) = \text{constant}$$

$$i(t) = i(T_2) = I T_1 \omega_0 \sin[\omega_0(T_2 - T_1)]$$

$$\text{for } T_2 \leq t \leq T_3$$

doing KVL around the loop I tells us that  $v(t)$  must equal 0.

$$v(t) = 0, \quad T_2 \leq t \leq T_3$$

(4)

(D) @  $t = T_3$ ,  $v(T_3) = 0$

$$\Rightarrow v(t) = \frac{I}{C} (t - T_3), \quad T_3 \leq t \leq T_4$$

$v_2(t) = 0$ ,  $i(t)$  must remain constant

$$i(t) = I T_1 \omega_0 \quad T_3 \leq t \leq T_4$$

(E) @  $t = T_4$ ,  $v(T_4) = \frac{I}{C} (T_4 - T_3)$

$$i(T_4) = I T_1 \omega_0$$

Similar to Part B:

$$\frac{d^2 v(t)}{dt^2} + \frac{1}{LC} v(t) = 0 \quad \omega_0 = \frac{1}{\sqrt{LC}}$$

The general solution see in class is:

$$v(t) = A_1 \cos[\omega_0(t - T_4)] + A_2 \sin[\omega_0(t - T_4)]$$

$$v(T_4) = \frac{I}{C} (T_4 - T_3) \Rightarrow A_1 = \frac{I}{C} (T_4 - T_3)$$

$$i(t) = -c \frac{dv(t)}{dt} \Rightarrow i(T_4) = -c \frac{dv(t)}{dt} = I T_1 \omega_0$$

$$\frac{dv(t)}{dt} = - \frac{I T_1 \omega_0}{C}$$

(5)

$$\frac{dv(t)}{dt} = -A_1 \omega_0 \sin[\omega_0 (t - T_4)] + A_2 \omega_0 \cos[\omega_0 (t - T_4)]$$

$$\frac{dv(T_4)}{dt} = +A_2 \omega_0 = -\frac{I T_1}{c} \omega_0$$

$$A = -\frac{I T_1}{c}$$

$$v(t) = \frac{I}{c} (T_4 - T_3) \cos[\omega_0 (t - T_4)] - \frac{I T_1}{c} \sin[\omega_0 (t - T_4)]$$

$$z(t) = I \omega_0 \left[ (T_4 - T_3) \sin[\omega_0 (t - T_4)] + T_1 \cos[\omega_0 (t - T_4)] \right]$$

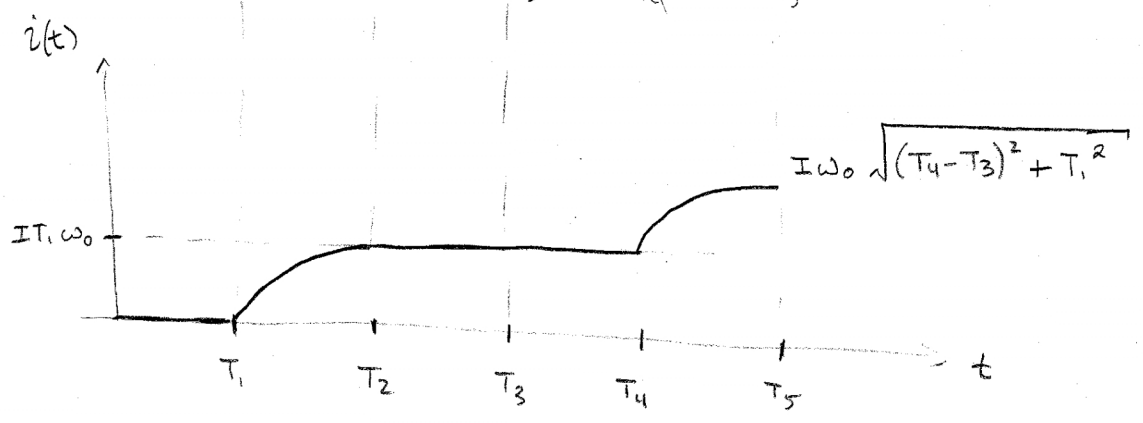
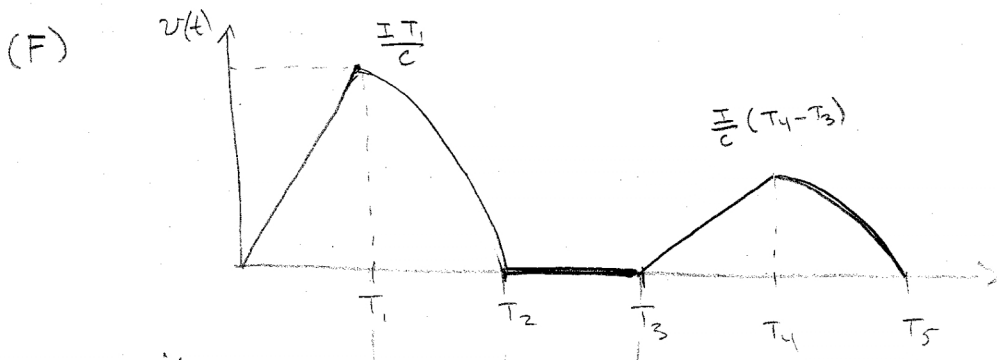
for  $T_4 \leq t \leq T_5$

$$v(T_5) = 0$$

$$\Rightarrow \frac{I}{c} (T_4 - T_3) \cos[\omega_0 (T_5 - T_4)] = \frac{I T_1}{c} \sin[\omega_0 (T_5 - T_4)]$$

$$\tan(\omega_0 (T_5 - T_4)) = \frac{T_4 - T_3}{T_1}$$

$$T_5 = T_4 + \frac{1}{\omega_0} \tan^{-1} \left( \frac{T_4 - T_3}{T_1} \right)$$



2M 8.2

$$E_c = \frac{1}{2} C v^2(T_1) = \frac{1}{2} C \frac{I^2 T_1^2}{C^2} = \frac{1}{2} \frac{I^2 T_1^2}{C}$$

$$E_c = \frac{1}{2} \frac{I^2 T_1^2}{C}$$

$$E_L = \frac{1}{2} L i^2(T_2) = \frac{1}{2} \frac{I^2 T_1^2}{C}$$

$$i^2(T_2) = \frac{I^2 T_1^2}{LC} = \frac{I^2 T_1^2}{1/\omega_0^2}$$

$$i^2(T_2) = I^2 T_1^2 \omega_0^2$$

$$i(T_2) = \pm I T_1 \omega_0$$

Since the inductor is being charged w/ positive  $v_c(t)$ , we choose the positive solution.

$$i(T_2) = I T_1 \omega_0$$

$$(c) @ t = T_4, v(T_4) = \frac{I}{C} (T_4 - T_3)$$

$$E_c = \frac{1}{2} C v^2(T_4) = \frac{1}{2} C \frac{I^2 (T_4 - T_3)^2}{C^2}$$

$$E_c = \frac{1}{2} \frac{I^2 (T_4 - T_3)^2}{C}$$

(8)

(D) at  $T_5$  the energy from the capacitor is transferred to the inductor which already had  $\frac{1}{2} \frac{I^2 T_1^2}{C}$  stored.

$$\therefore E_L(T_5) = \frac{1}{2} L i^2(T_5)$$

$$\frac{1}{2} L i^2(T_5) = \frac{1}{2} \frac{I^2 T_1^2}{C} + \frac{1}{2} \frac{I^2 (T_4 - T_3)^2}{C}$$

↑  
Part (C)

$$\therefore i_L(T_5) = I \omega_0 \sqrt{(T_4 - T_3)^2 + T_1^2}$$

(E) For each cycle,  $v_c = \frac{I}{C} T$  after  $S_1$  is open

At this point  $E_c = \frac{1}{2} C \left(\frac{I}{C} T\right)^2 = \frac{1}{2} \frac{I^2 T^2}{C}$

In the 2<sup>nd</sup> part of the cycle, this is transferred to the inductor:

After 1<sup>st</sup> cycle:  $E_L = \frac{1}{2} \frac{I^2 T^2}{C}$

2<sup>nd</sup> cycle  $E_L = 2 \cdot \frac{1}{2} \frac{I^2 T^2}{C}$

After  $n$  cycles  $E_L = \frac{n}{2} \frac{I^2 T^2}{C} = \frac{1}{2} L i_L^2(nT)$

$$i_L^2(nT) = \frac{n I^2 T^2}{LC}$$

$$\Rightarrow i_L(nT) = I T \omega_0 \sqrt{n}$$



Problem 8.3

(9)

(A) See attached graph

$$(B) \quad \omega = 2\pi f = \frac{2\pi}{T} = \frac{2\pi}{1.32\text{ms} - 1.2\text{ms}}$$

$$\omega = 52.4 \times 10^3 \frac{\text{rad}}{\text{s}}$$

$$\tau \approx 0.18 \text{ ms}$$

(C) Using KVL:

$$v_{IN} = v_R + v_L + v_C$$
$$= iR + L \frac{di}{dt} + v_C$$

$$v_C = C \frac{dv_C}{dt}$$

$$\frac{dv_{IN}}{dt} = R \frac{di}{dt} + L \frac{d^2i}{dt^2} + \frac{i}{C}$$

$$\frac{d^2i}{dt^2} + \frac{R}{L} \frac{di}{dt} + \frac{i}{LC} = \frac{1}{L} \frac{dv_{IN}}{dt}$$

(D) If the network is initially at rest.  $i = 0$

$$i(0^-) = 0 \quad v_C(0^-) = V_{IN1} \quad v_L(0^-) = 0$$
$$v_R(0^-) = 0 \quad \frac{di}{dt}(0^-) = 0$$

Just after the step,  $i$  will still be zero

$$i(0^+) = 0 \quad v_C(0^+) = V_{IN1} \quad v_L(0^+) = V_{IN2} - V_{IN1}$$
$$v_R(0^+) = 0 \quad \frac{di}{dt}(0^+) = \frac{V_{IN2} - V_{IN1}}{L}$$

(E) for  $t \rightarrow \infty$  and a constant inputs, the capacitor looks like an open circuit.  $\Rightarrow i \rightarrow 0$

$\therefore i(\infty) = 0$

As we saw in Lecture an RLC circuit will ring like  $\sin()$  but amplitude of  $i$  will decay. This gives the form.

$i(t) = I \sin(\omega t + \phi) e^{-\alpha t}$

for  $i(0) = I \sin(\phi) = 0$

$\therefore \phi = 0$

$\alpha = \frac{R}{2L}$   
 $\omega = \omega_d = \sqrt{\omega_0^2 - \alpha^2} = \sqrt{\frac{1}{LC} - \frac{R^2}{4L^2}}$

$\left. \frac{di}{dt} \right|_{0^+} = I \omega \cos(0) = \frac{v_L(0^+)}{L} = \frac{V_{IN2}}{L} = \frac{V_{IN2} - V_{IN1}}{L}$

$I = \frac{V_{IN2} - V_{IN1}}{\omega L}$

(F)  $v_{IN} = v_R + v_{out}$

$v_{IN} = i(t) \cdot R + v_{out}$

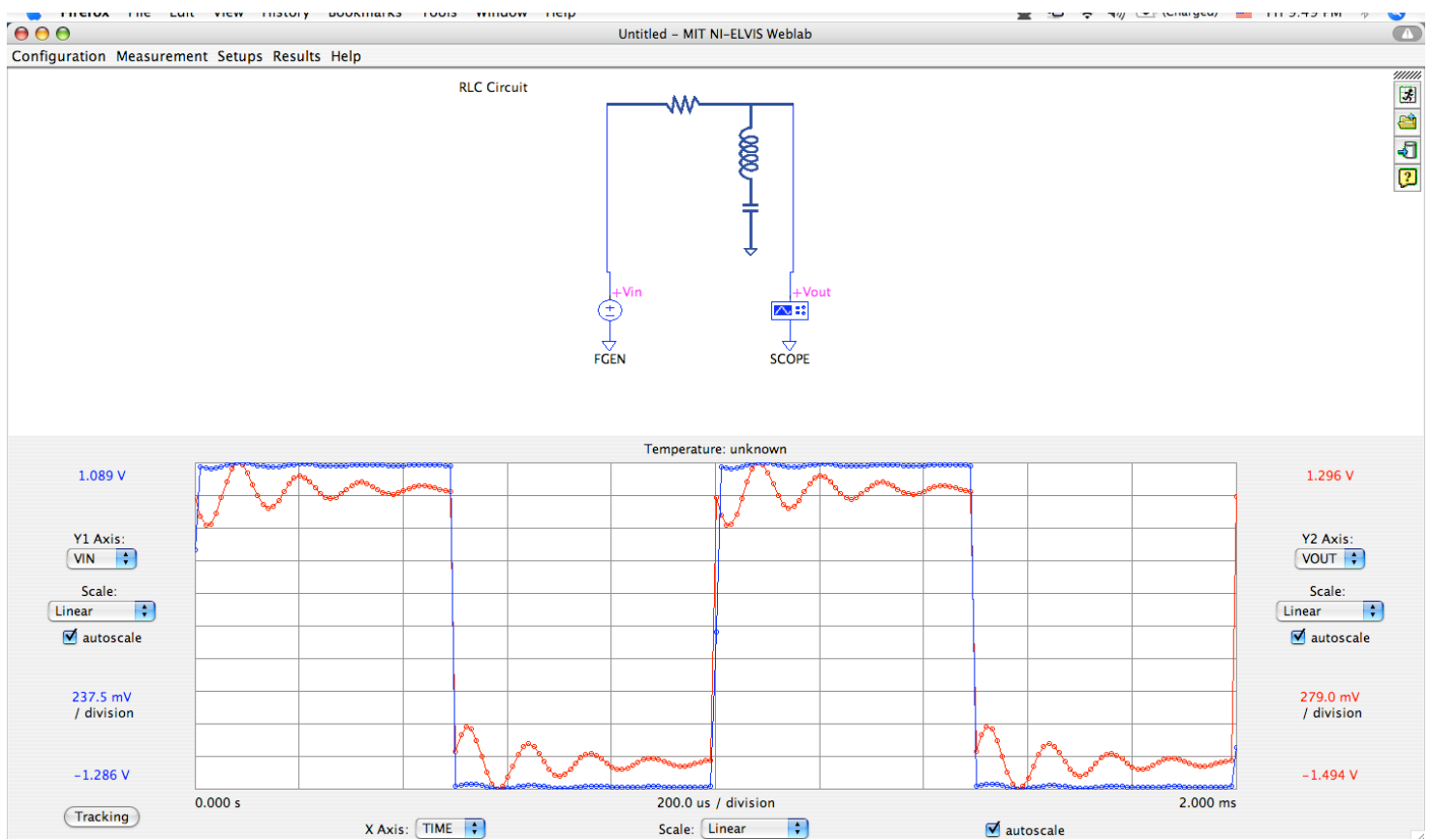
For  $V_{IN2} \rightarrow V_{IN1}$ :  $v_{out} = V_{IN2} - IR \sin(\omega t) e^{-\alpha t}$   
For  $V_{IN2} \rightarrow V_{IN1}$ :  $v_{out} = V_{IN1} + IR \sin(\omega t) e^{-\alpha t}$

$$(G) \quad \omega = \sqrt{\frac{1}{LC} - \frac{R^2}{4L^2}} = 52.4 \times 10^3$$

$$\alpha = \frac{R}{2L} = 0.18 \times 10^{-3}$$

$$\frac{1}{LC} = 2.75 \times 10^9$$

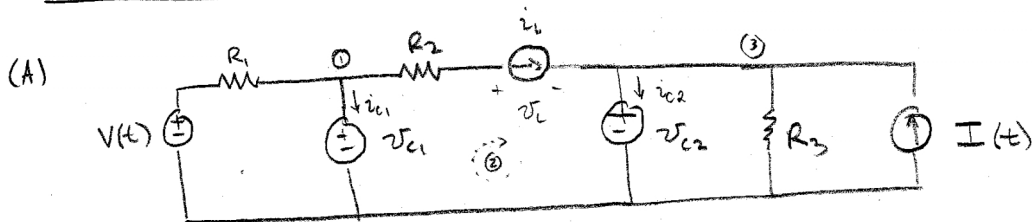
(11)



Problem 8.3A

Problem 8.4

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(B) c ①: 
$$\frac{V(t) - v_{c1}}{R_1} - i_{c1} - i_L = 0$$

$$i_{c1} = \frac{V(t) - v_{c1}}{R_1} - i_L$$

c ②: 
$$v_{c1} - i_L R_2 - v_L - v_{c2} = 0$$

$$v_L = v_{c1} - i_L R_2 - v_{c2}$$

c ③: 
$$i_L - i_{c2} - \frac{v_{c2}}{R_3} + I(t) = 0$$

$$i_{c2} = i_L + I(t) - \frac{v_{c2}}{R_3}$$

(C) 
$$v_L = L \frac{di_L}{dt}$$

$$i_{c2} = C \frac{dv_{c2}}{dt}$$

From above: 
$$C \frac{dv_{c1}}{dt} = \frac{V(t) - v_{c1}}{R_1} - i_L$$

$$L \frac{di_L}{dt} = v_{c1} - i_L R_2 - v_{c2}$$

$$C \frac{dv_{c2}}{dt} = i_L + I(t) - \frac{v_{c2}}{R_3}$$

$$\frac{d}{dt} \begin{bmatrix} i_c(t) \\ v_{c_1}(t) \\ v_{c_2}(t) \end{bmatrix} = \begin{bmatrix} -R_2/L & 1/L & -1/L \\ -1/C_1 & -1/R_1C_1 & 0 \\ 1/C_2 & 0 & -1/C_2R_2 \end{bmatrix} \begin{bmatrix} i_c(t) \\ v_{c_1}(t) \\ v_{c_2}(t) \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 1/R_1C_1 \\ 1/C_2 \end{bmatrix} \begin{bmatrix} I(t) \\ V(t) \end{bmatrix}$$

(14)