Basic Radar 3.2: Statistical Properties ISR Power Estimates

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Statistical Properties of ISR Voltages

ISR signals are complex-valued, zero-mean, random phase, Gaussian random vaiables with variances related to their power P:

$$V = V_R + jV_I$$

$$E\{V_R\} = E\{V_I\} = 0$$

$$E\{V_R^2\} = E\{V_I^2\} = \frac{1}{2}P \qquad E\{V_R V_I\} = 0$$

$$E\left\{|V|^2\right\} = E\{V_R^2 + V_I^2\} = P$$

$$E\{V_R^4\} = E\{V_I^4\} = \frac{3}{4}P^2 \qquad E\{V_R^2 V_I^2\} = E\{V_R^2\}E\{V_I^2\} = \frac{1}{4}P^2$$

$$Var\left\{|V|^2\right\} = E\left\{\left(|V|^2\right)^2\right\} - \left(E\left\{|V|^2\right\}\right)^2$$

$$= E\{V_R^4 + V_I^4 + 2V_R^2 V_I^2\} - \left(E\{V_R^2 + V_I^2\}\right)^2$$

$$= 2P^2 - P^2 = P^2$$

Signal and Noise Components Are Both Gaussian

Both the ionospheric signal and noise contributions to the received voltages are individually Gaussian random variables.

$$V = V_S + V_N$$
$$E\left\{V_S V_N^*\right\} = 0$$
$$E\left\{|V_S|^2\right\} = S$$
$$E\left\{|V_N|^2\right\} = N$$
$$E\left\{|V|^2\right\} = S + N = P$$

This is unlike other types of radar problems where the signals are treated as deterministic quantities.

Power Estimation

Given K voltage samples with unknown signal power S, a known noise power N, and total power $P = S + N$, an estimate of the signal power is:

$$\hat{S} = \frac{1}{K} \sum_{n=0}^{K-1} |V_n|^2 - N$$

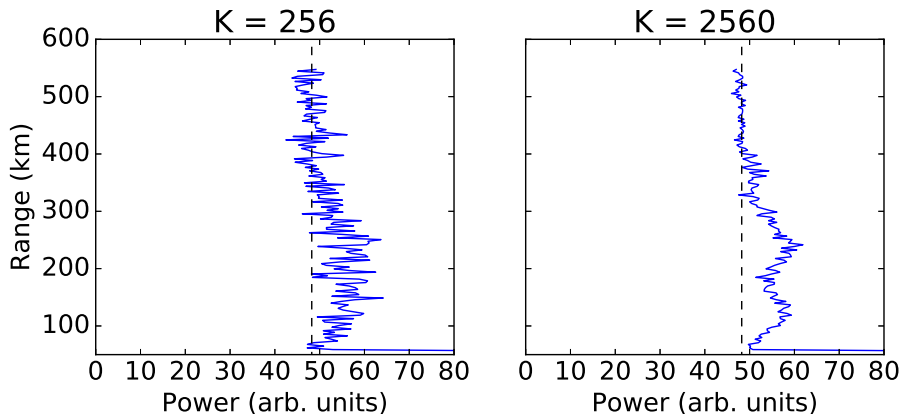Expected Value: $E\left\{\hat{S}\right\} = \frac{1}{K} \sum_{n=0}^{K-1} E\left\{|V_n|^2\right\} - N = P - N = S$

Variance (Invoke the Central Limit Theorem):

$$Var\left\{\hat{S}\right\} = Var\left\{\frac{1}{K} \sum_{n=0}^{K-1} |V_n|^2\right\} = \frac{1}{K} Var\left\{|V_n|^2\right\} = \frac{1}{K} P^2 = \frac{1}{K}\left(S + N\right)^2$$

Relative Error:

$$\frac{\sqrt{Var\left\{\hat{S}\right\}}}{S} = \frac{1}{\sqrt{K}} \frac{S + N}{S} = \frac{1}{\sqrt{K}}\left(1 + \frac{1}{S/N}\right)$$

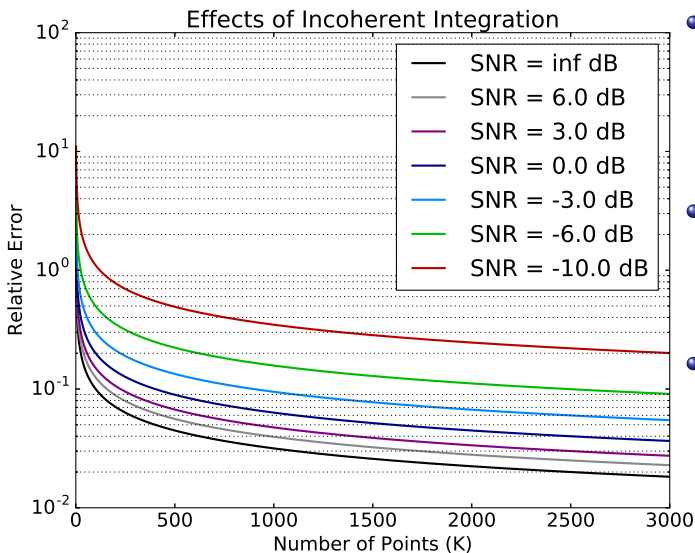# Statistical Uncertainty and SNR are Different Concepts

For $SNR = 0.25$:

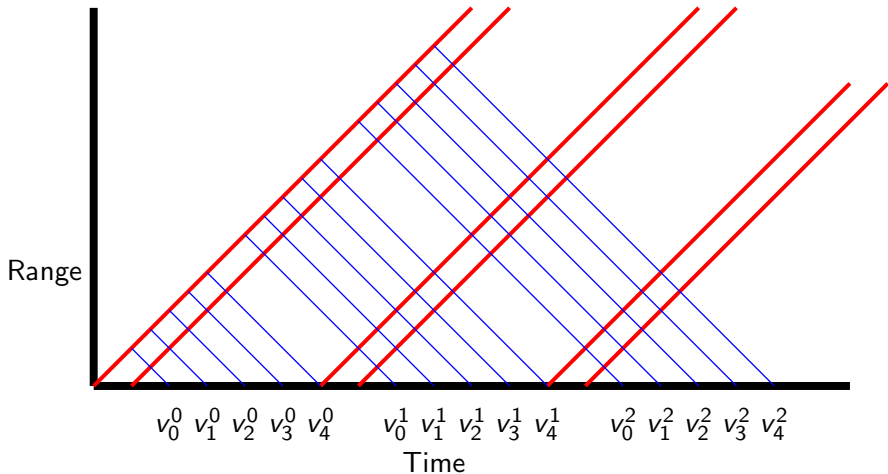$$K = 256 \rightarrow \text{Relative Error} = 31.25\%$$

$$K = 2560 \rightarrow \text{Relative Error} = 9.88\%$$

Required Integration Times

Effects of Incoherent Integration

- At $SNR = -3$ dB, 20% error requires $K = 225$.
- If the inter-pulse period is 5 ms, 225 pulses takes 1.125 s.
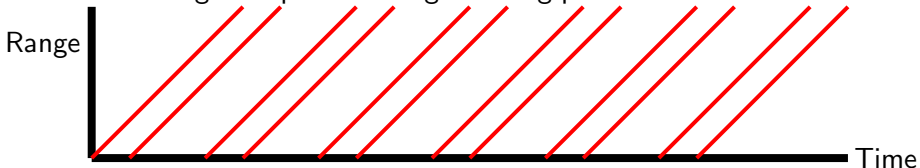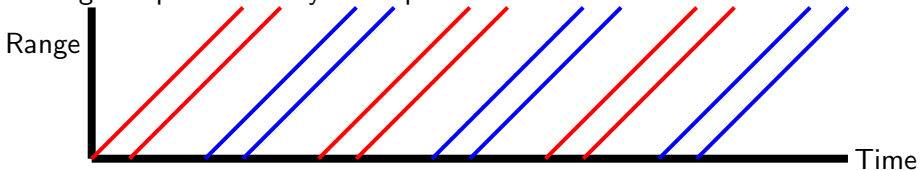- If you cycle between 25 beams, 225 pulses in all beams takes 28.125 s.

$$r_n = \frac{ct_n}{2} + m\frac{c\tau_{\mathrm{IPP}}}{2} \qquad \text{for any integer } m$$
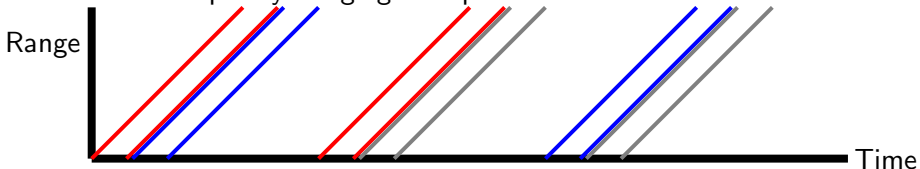
Exploiting Frequency Diversity

Pulses close together produce range aliasing problems:

Change frequencies every other pulse:

The RISR 3-frequency ImagingLP experiments:

Power Estimation Summary

- In ISR, both the signal and noise portions of the voltages are Gaussian random variables.
- The SNR is the ratio of the power in the signal and noise portions of the voltage.
- What actually matters for detectability is the relative error of our estimate of signal power, which depends on both SNR and the number of samples averaged together.

$$\frac{\sqrt{Var\left\{\hat{S}\right\}}}{S} = \frac{1}{\sqrt{K}}\left(1 + \frac{1}{S/N}\right)$$

- Some amount of averaging is always necessary, even in the $SNR \to \infty$ limit.
- For $SNR > 1$ it is more worthwhile to increase the effective number of samples than to keep increasing SNR further.