

# IS Fitting Examples, Ambiguities, and Constrained Analysis

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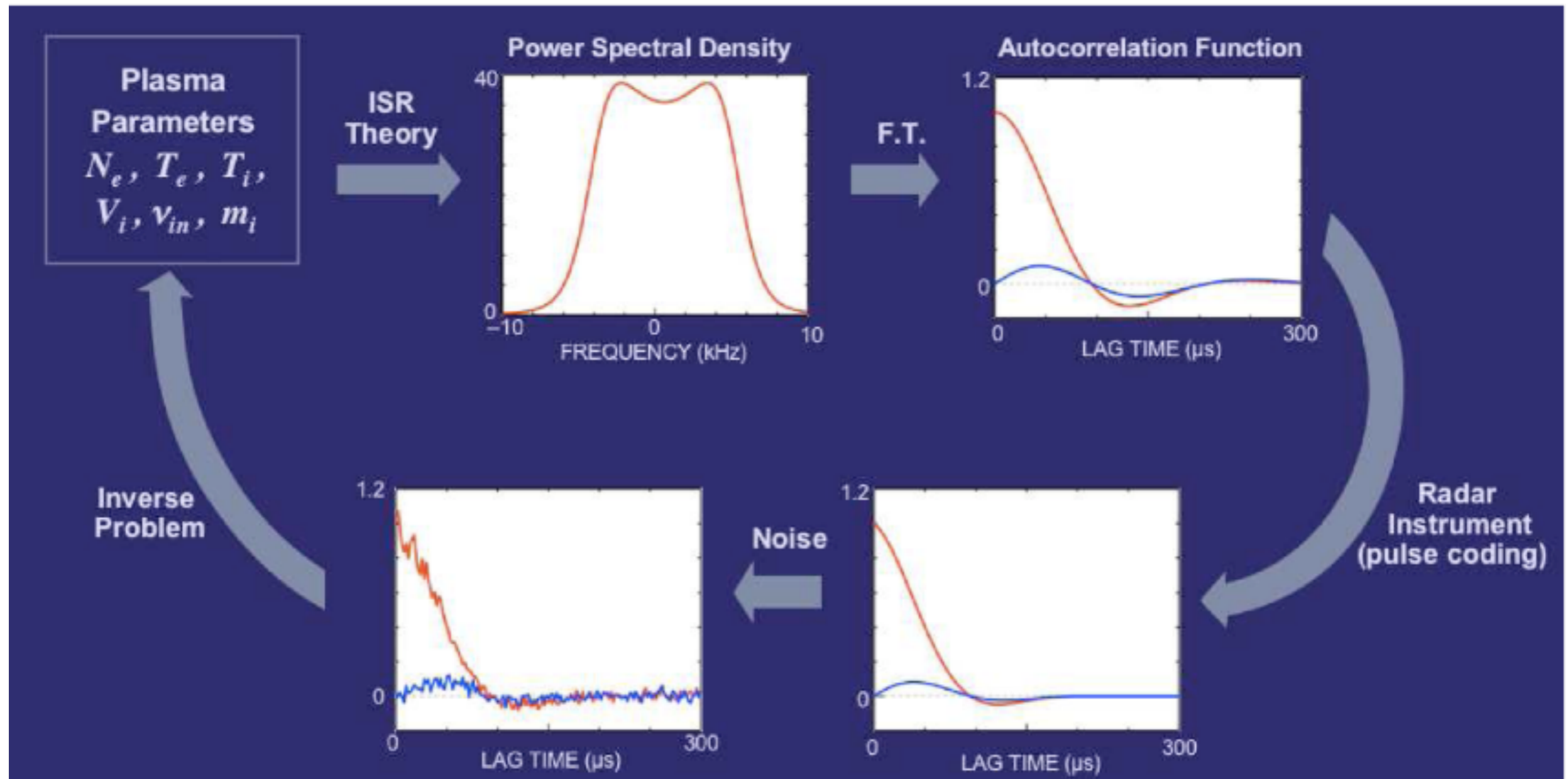
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Topics covered:

- Fitting data to a model
- Effects of noise and forward model ambiguities
- Resolving IS fitting ambiguities: constrained analysis

# ISR Practicalities: Data Reduction

NB: Power spectrum (freq domain)  $\leftrightarrow$  Autocorrelation function (time domain)



# Fitting data to a model

Goal: minimize

$$\chi^2(\mathbf{p}) = \sum_{m=1}^M \frac{[z_m - f_m(\mathbf{p})]^2}{\sigma_m^2}$$

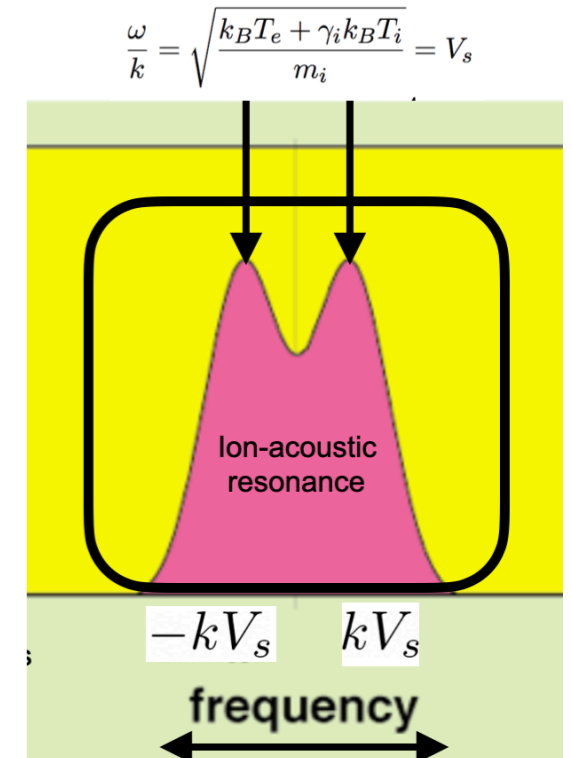
data (points to  $z_m$ )  
 Forward model (points to  $f_m(\mathbf{p})$ )  
 Parameter vector (points to  $\mathbf{p}$ )  
 "L2 Norm"  
 Measurement uncertainties (points to  $\sigma_m^2$ )

Minimize by iterating over parameter vector  $\mathbf{p}$ .

Some problems are linear least-squares: solvable in one step.  
 Others are nonlinear least-squares:  
 model has complicated variations with parameters.  
 Incoherent scatter is this type.

Many different fitting algorithms possible depending on how one analytically expands the minimization function:

- Gradient-search (Nelder-Mead simplex)
- Analytic expansion (parabolic surface)
- Levenberg-Marquardt (balance between gradient and analytic)
- Simulated annealing



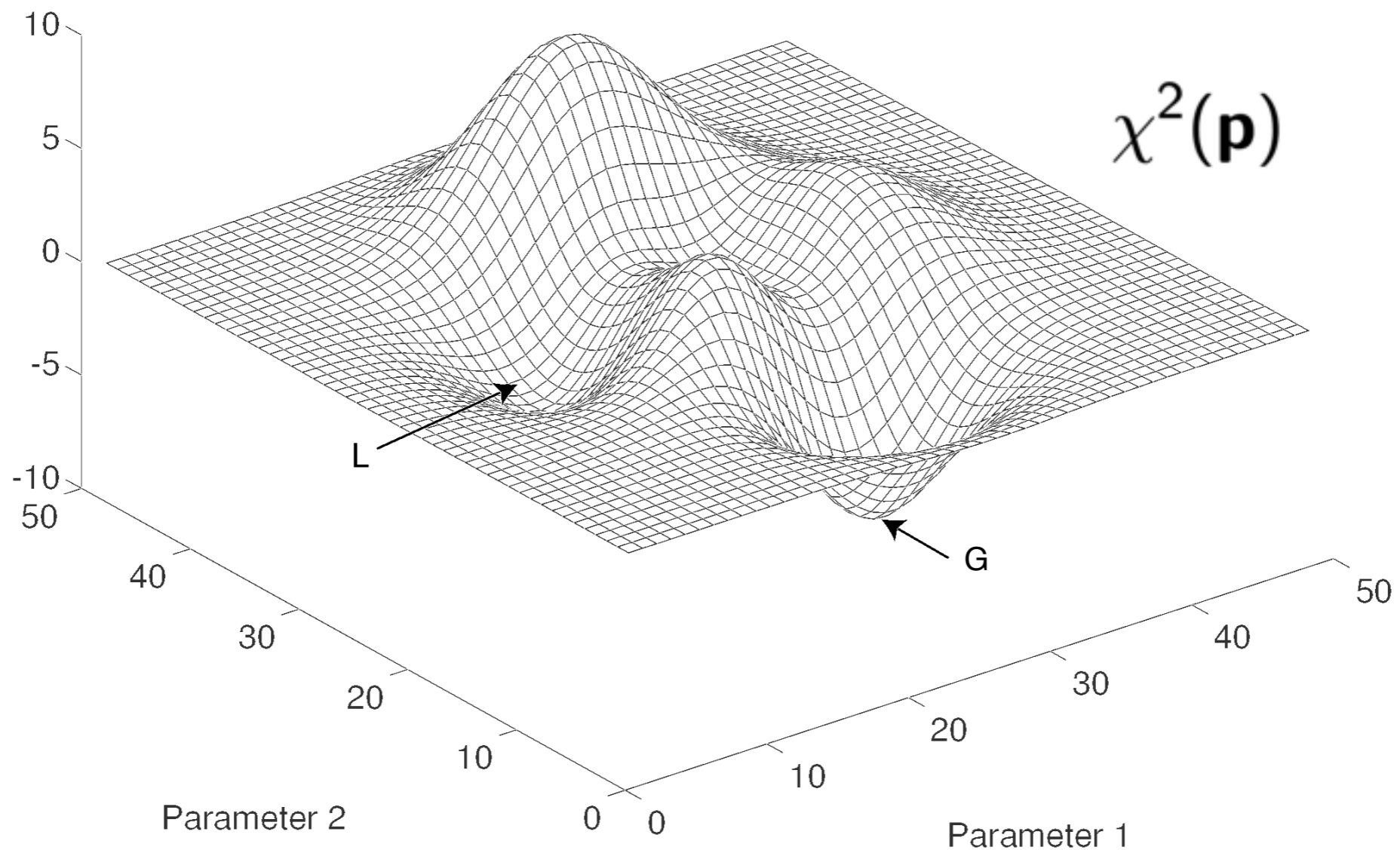
$$f_m(\mathbf{p})$$

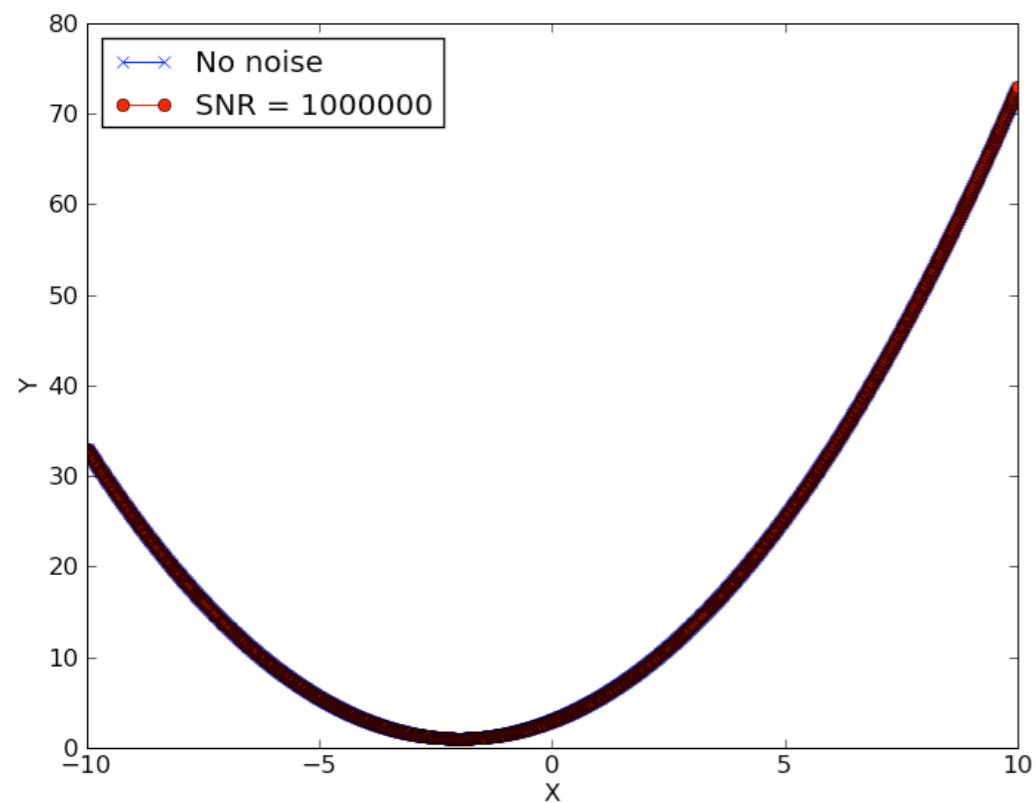
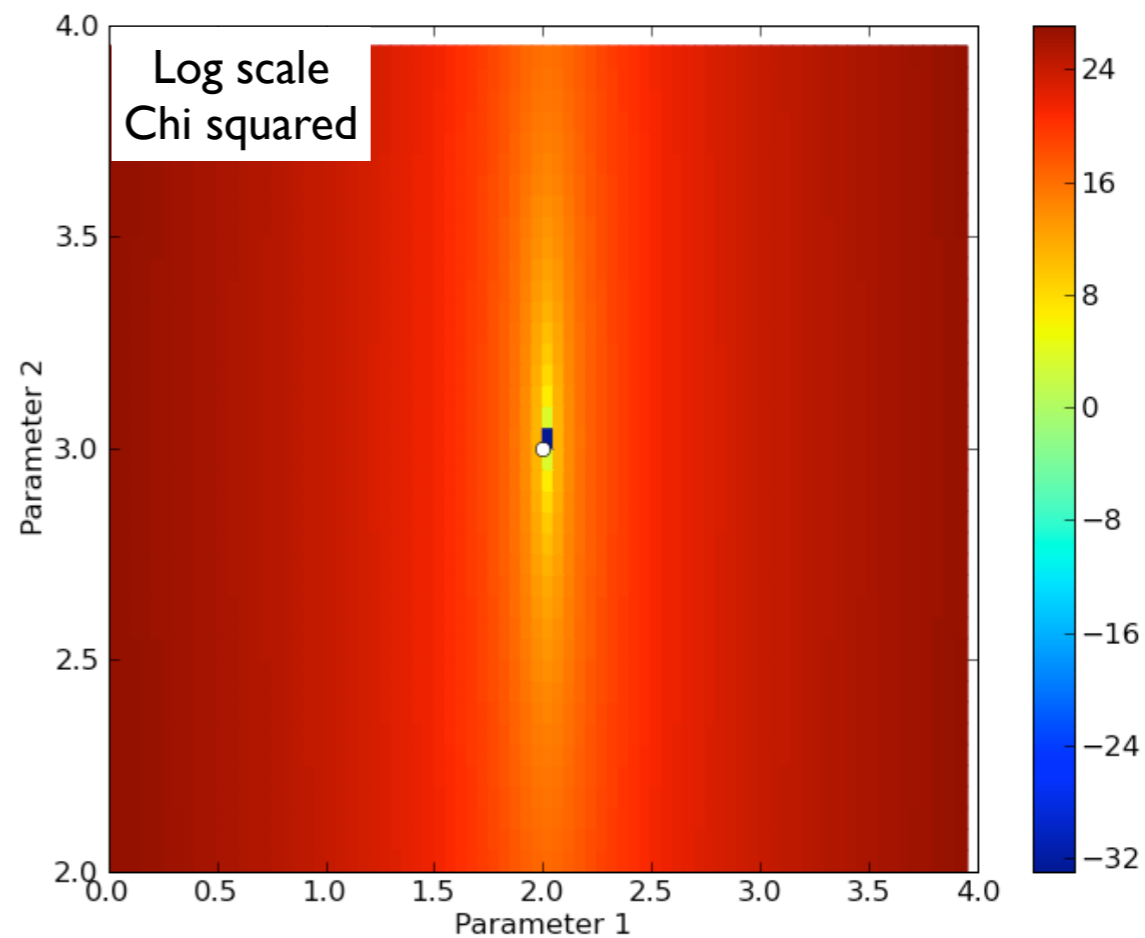
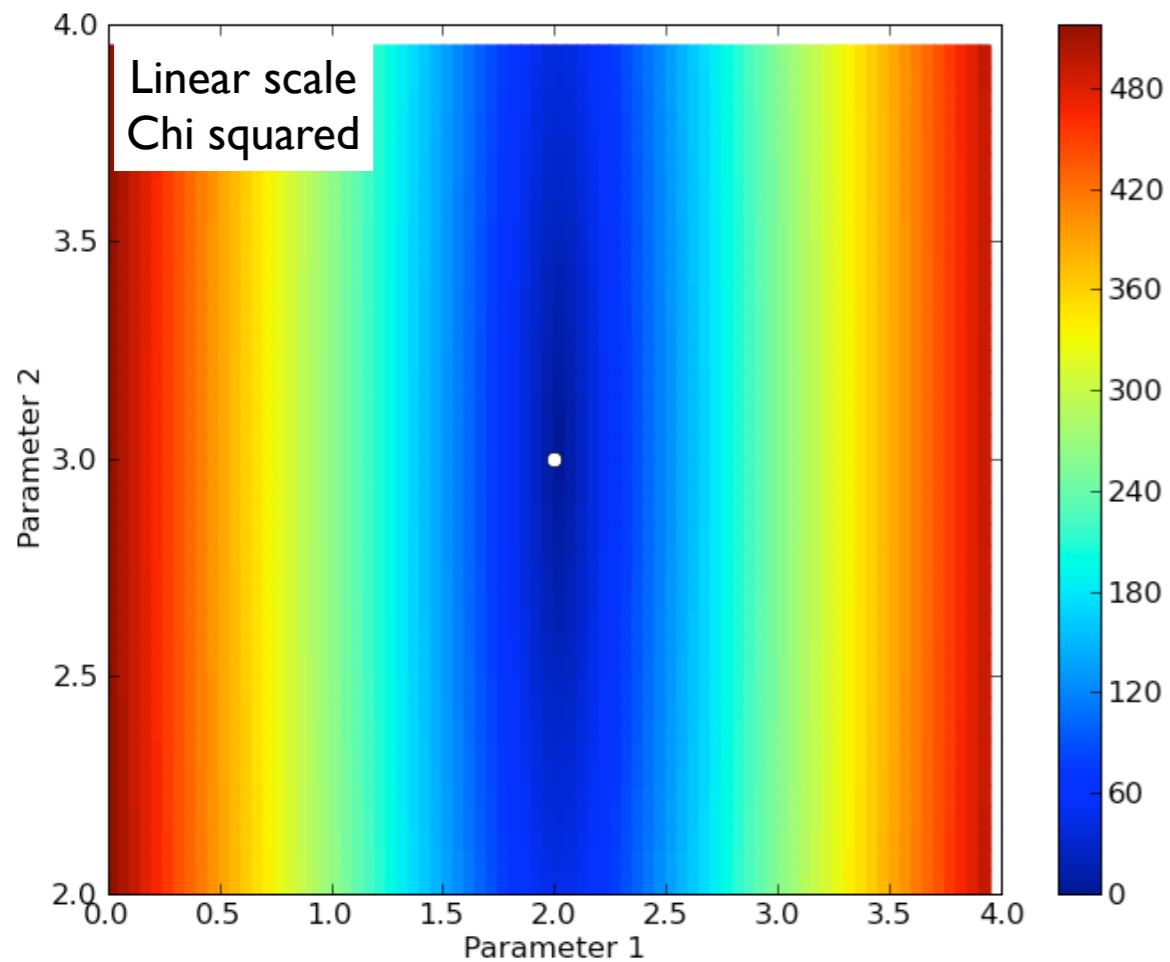
$$\mathbf{p} = [N_e, T_e, T_i, m_i]$$

# Incoherent Scatter Fit Ambiguities

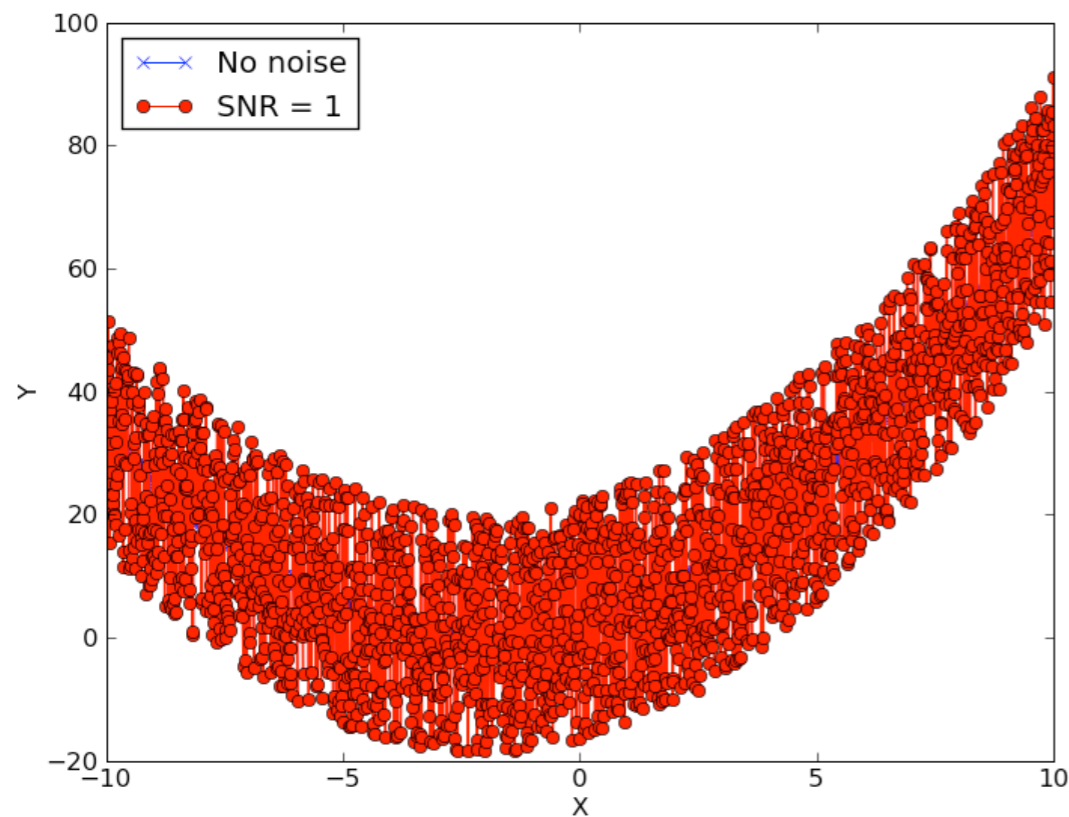
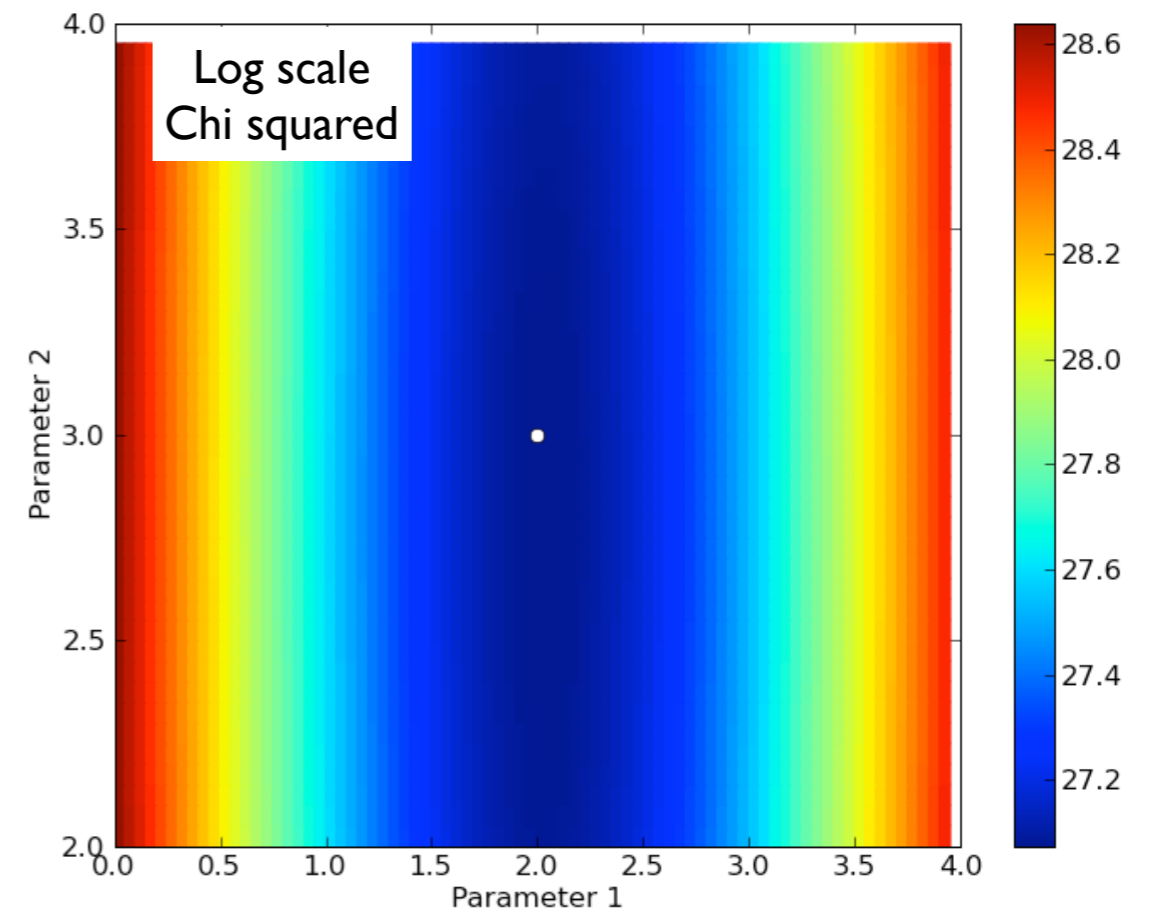
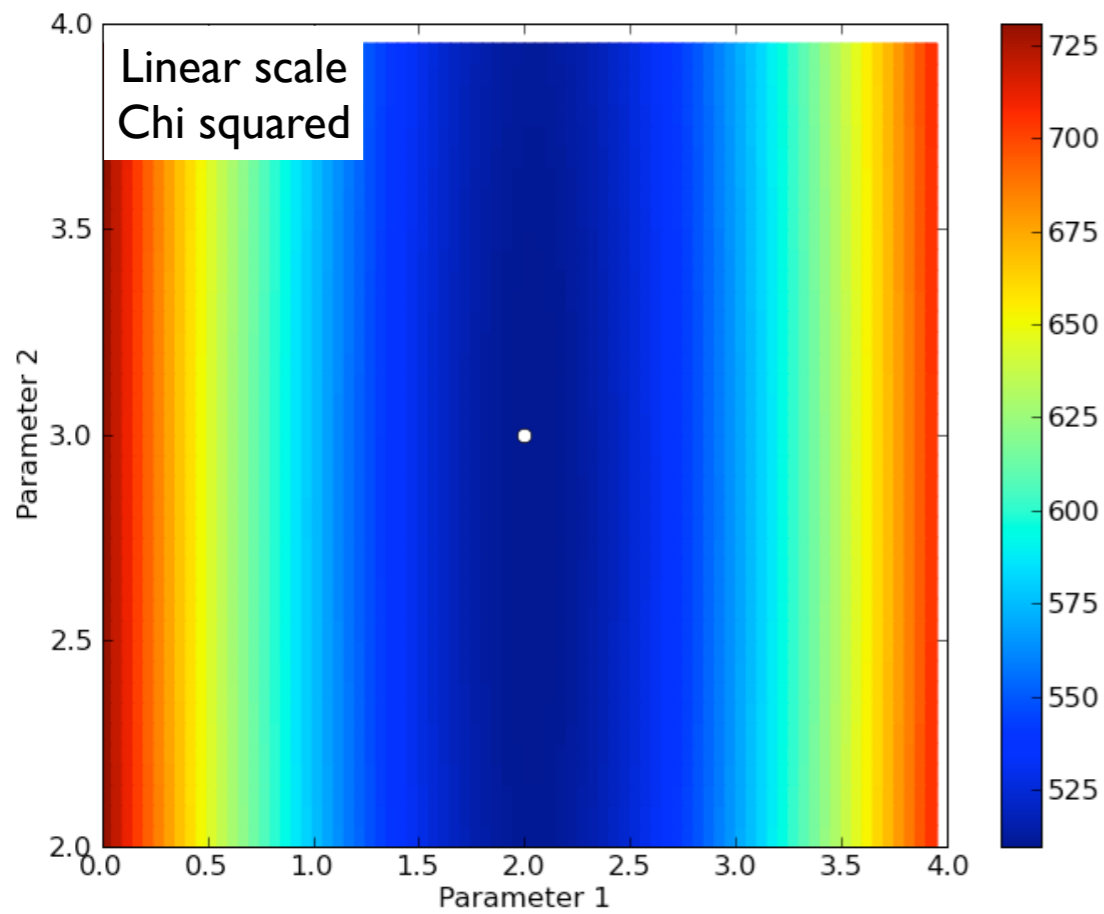
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L, G might both be valid parameter solutions. (**Local vs global** minimum)  
Might need to use constraints on the parameters to decide which one.

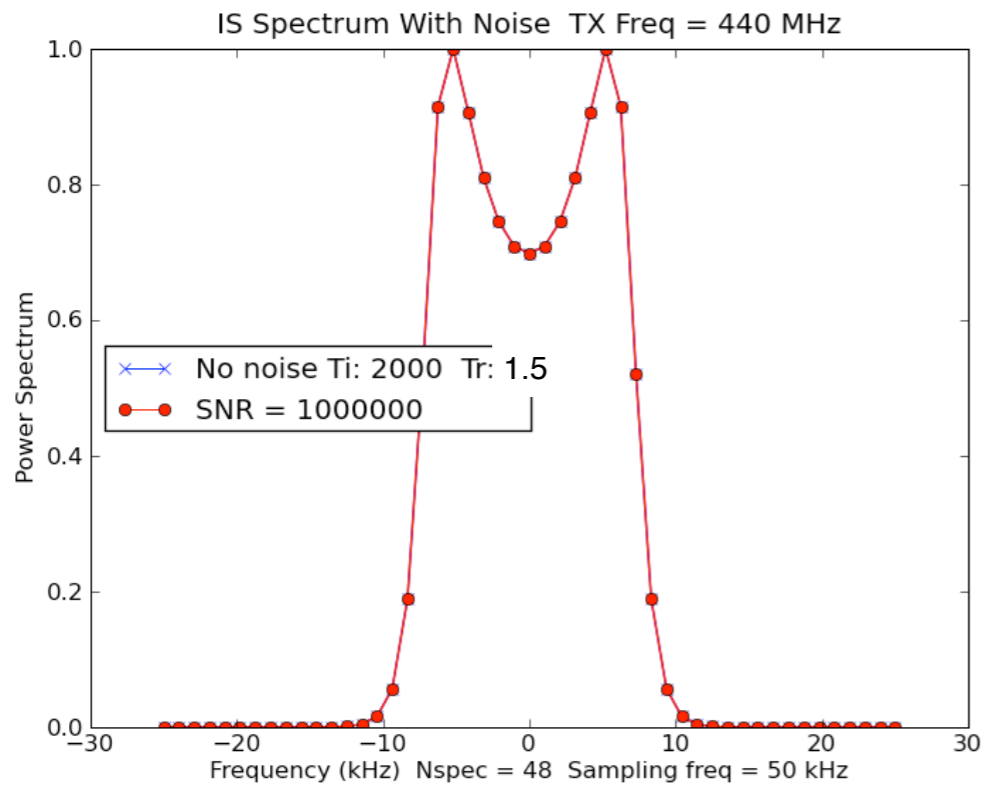
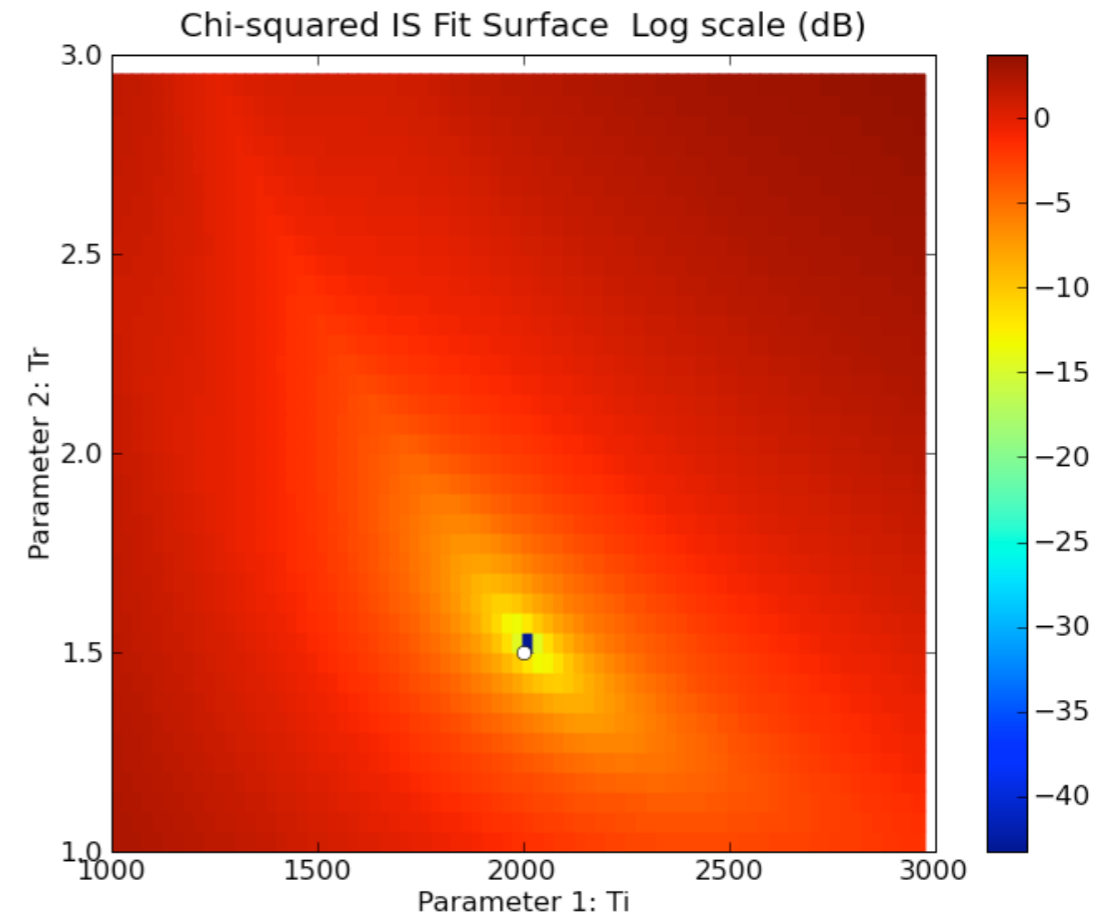
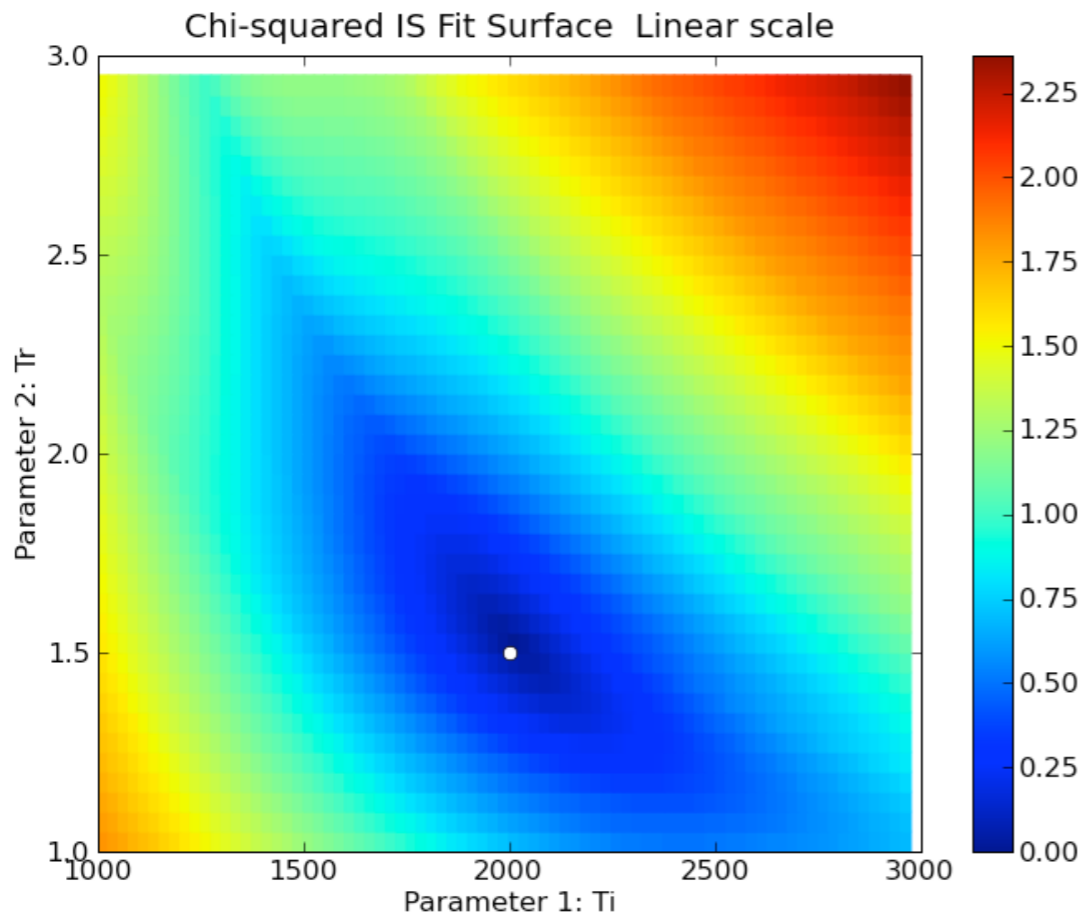




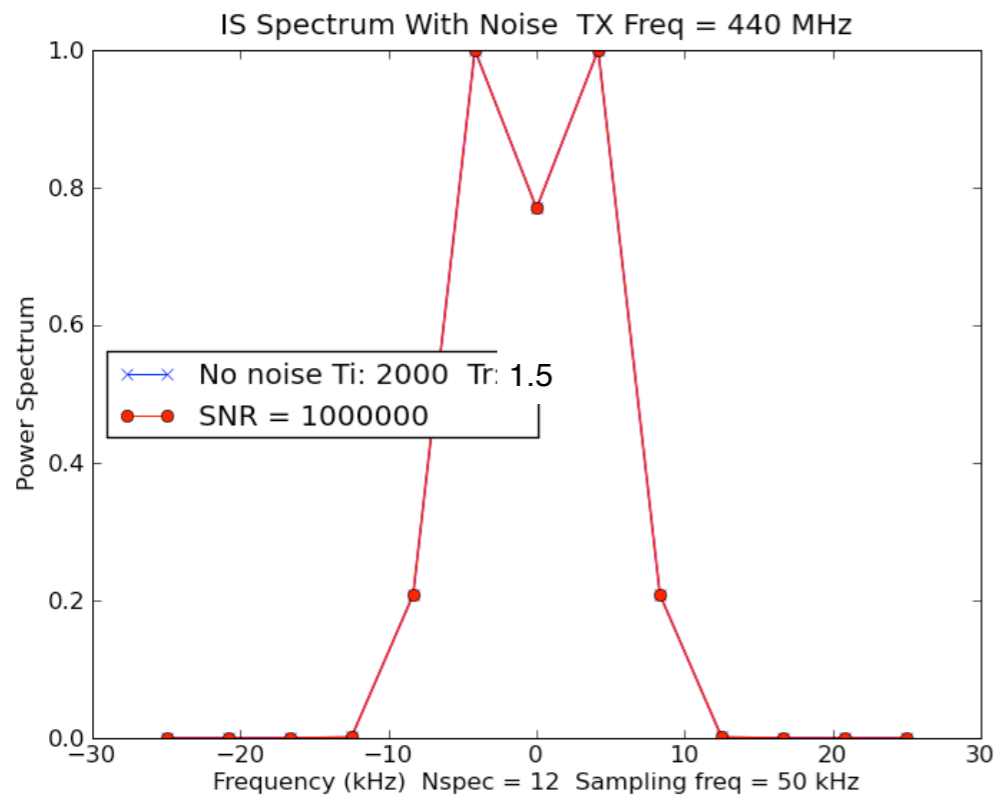
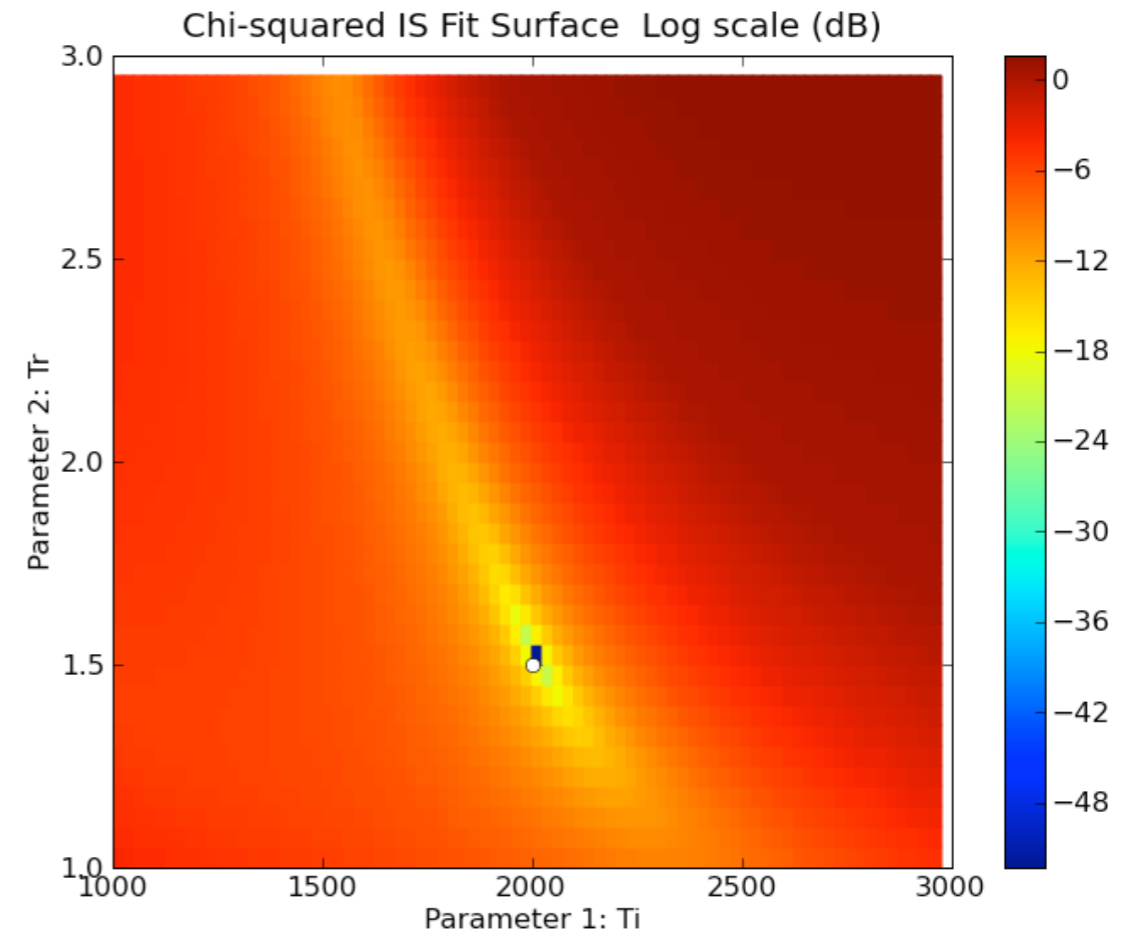
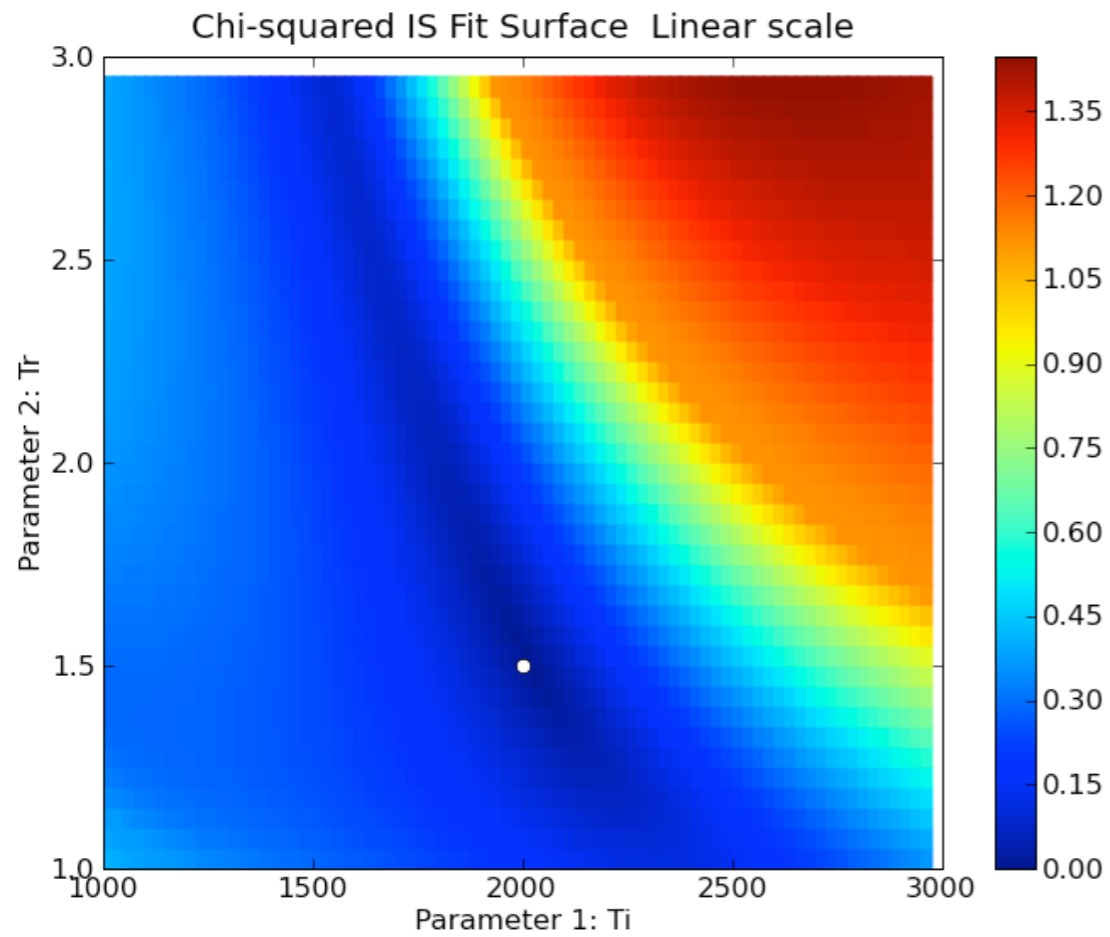
Parabola  
 $y = 0.5 x^2 + 2 x + 3$   
 Slope, intercept fit  
 No noise



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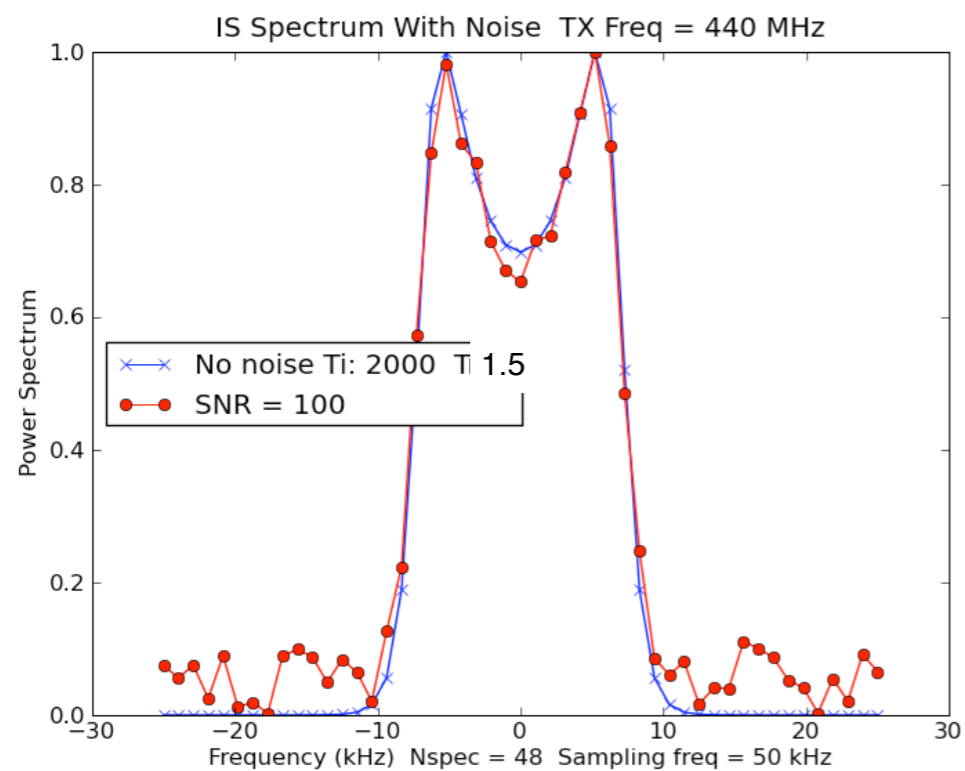
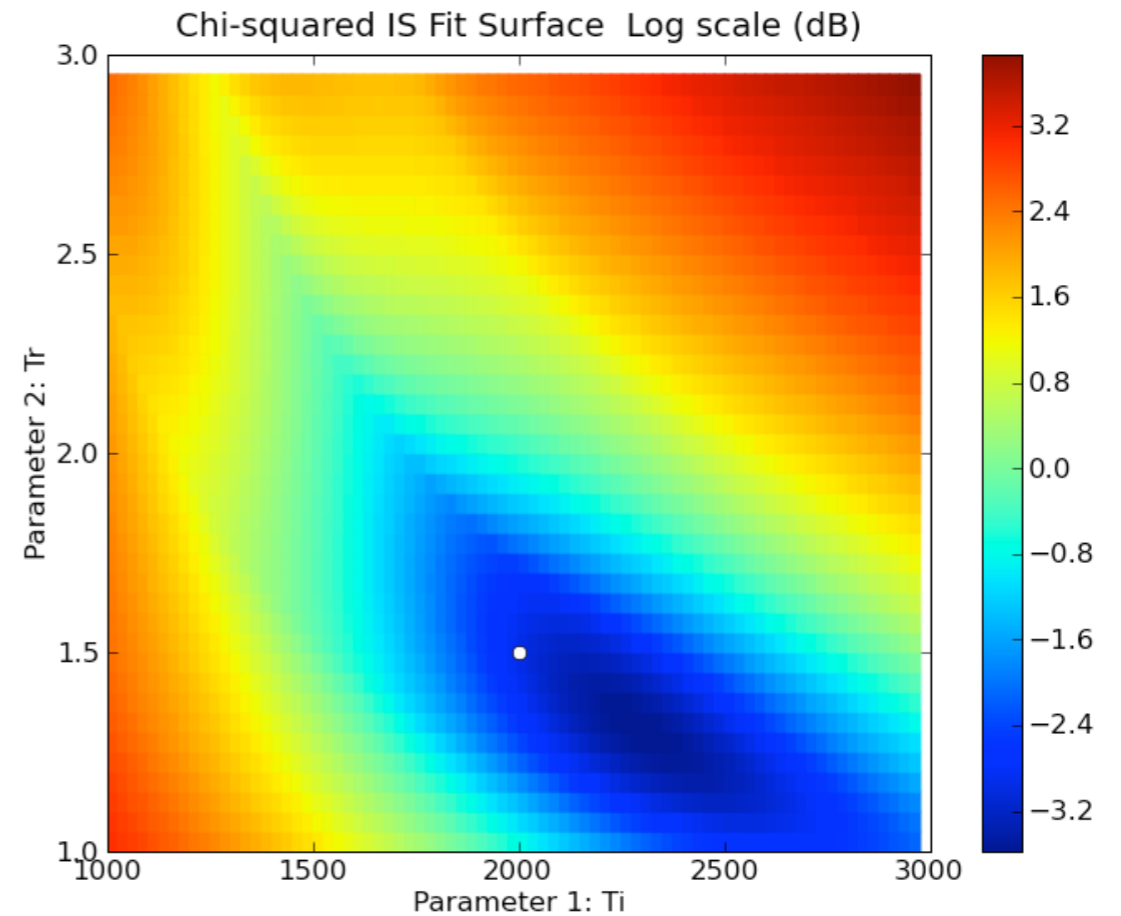
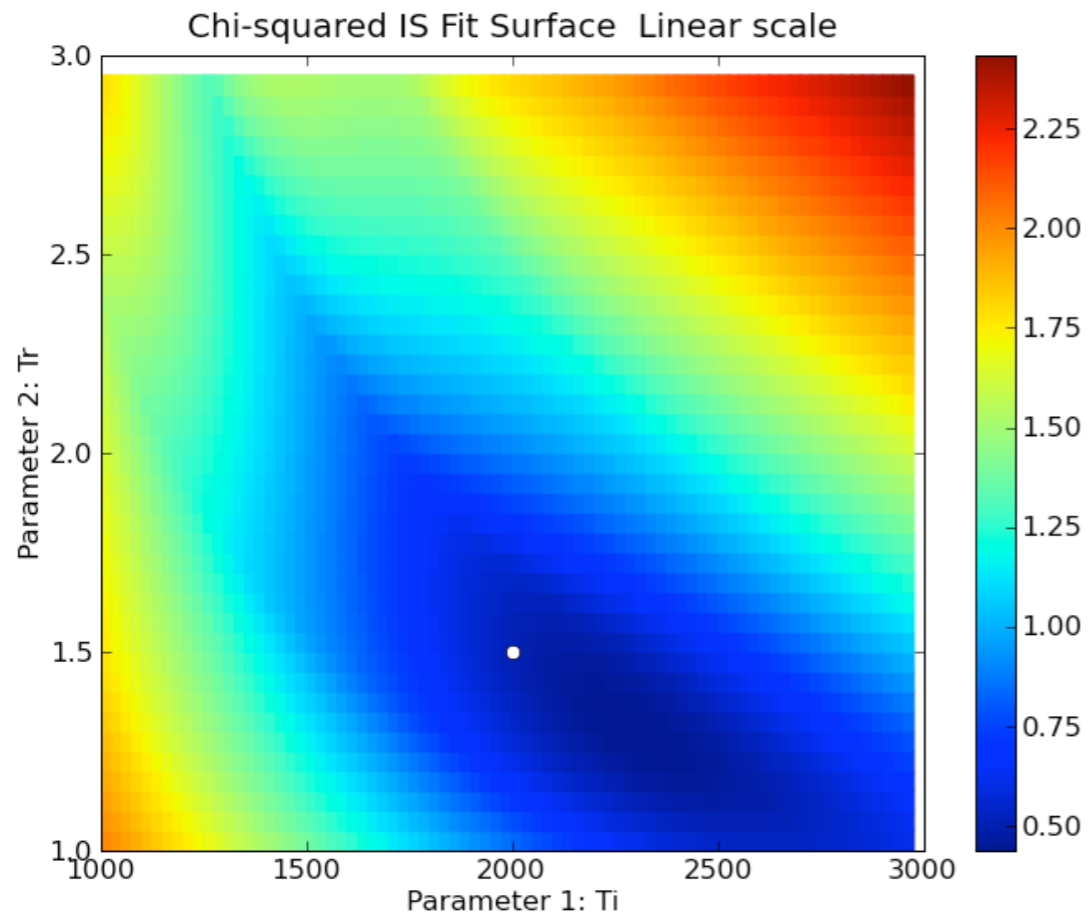


440 MHz IS Spectrum  
 Ti/Tr space  
 Ti = 2000 Tr = 1.5  
 No noise

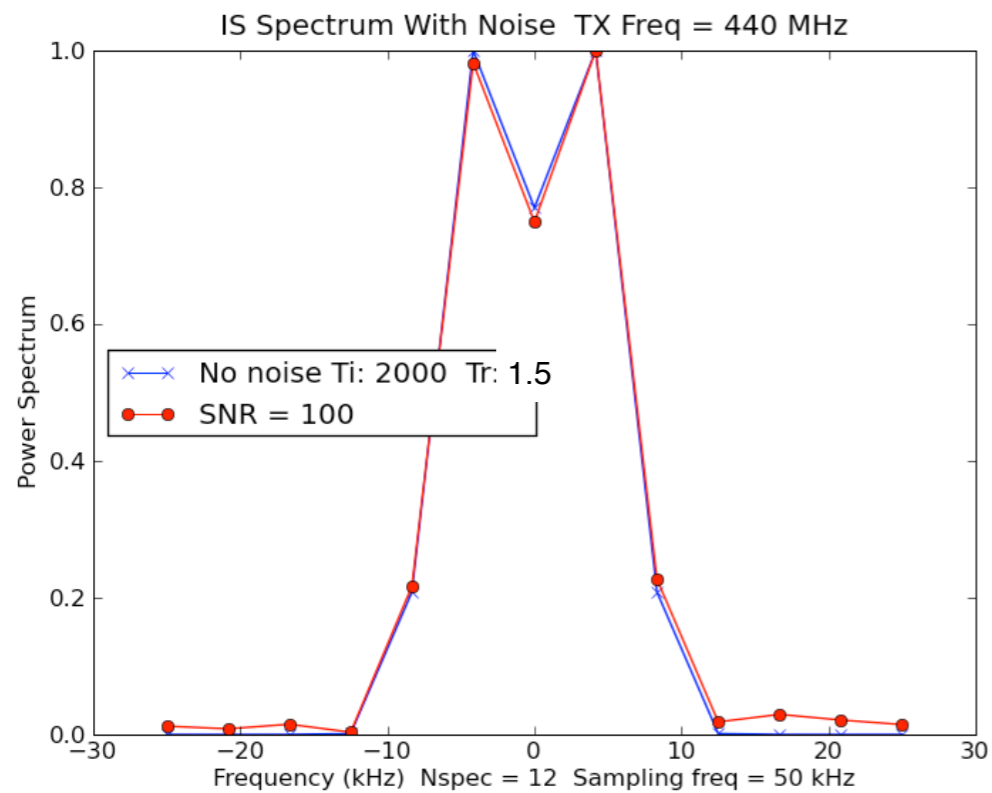
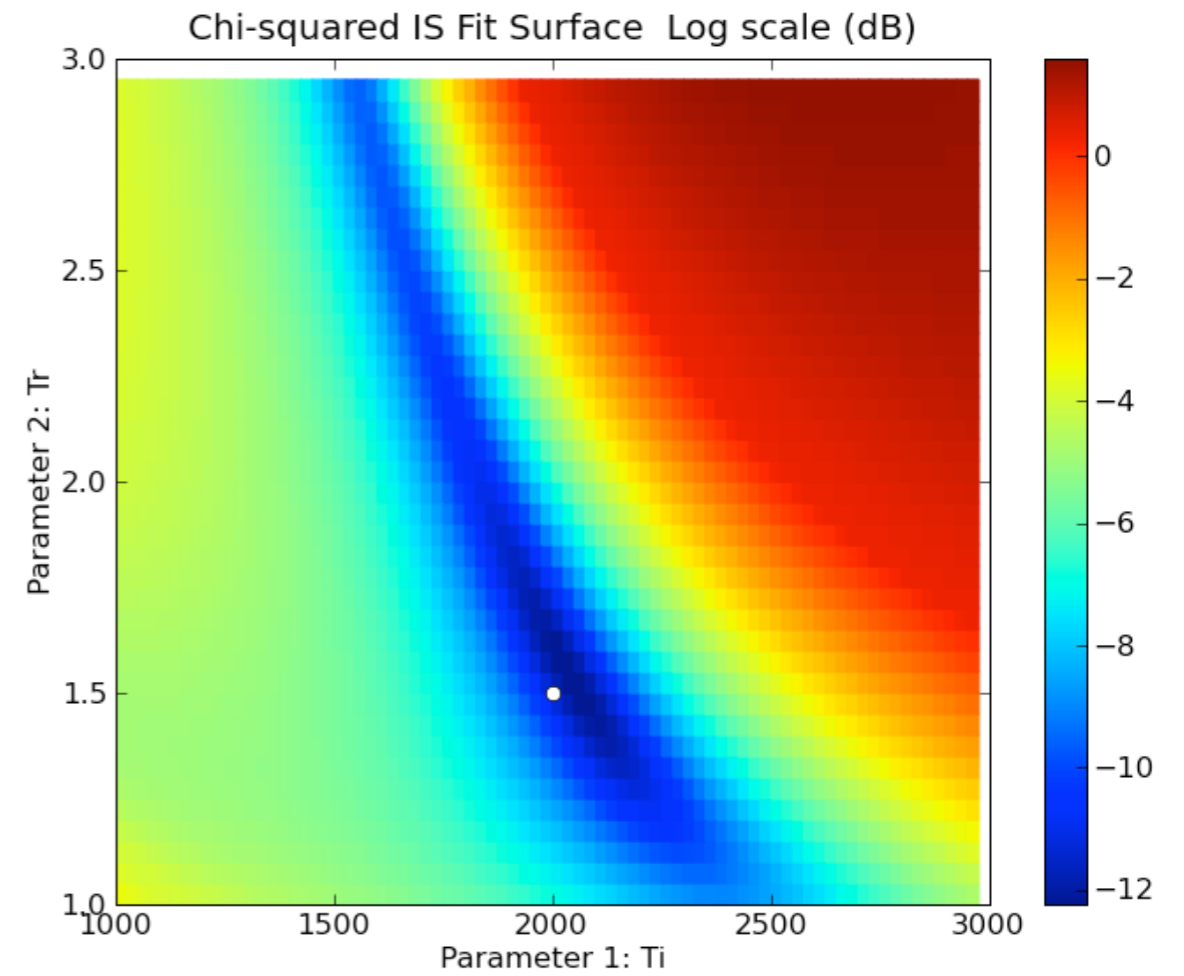
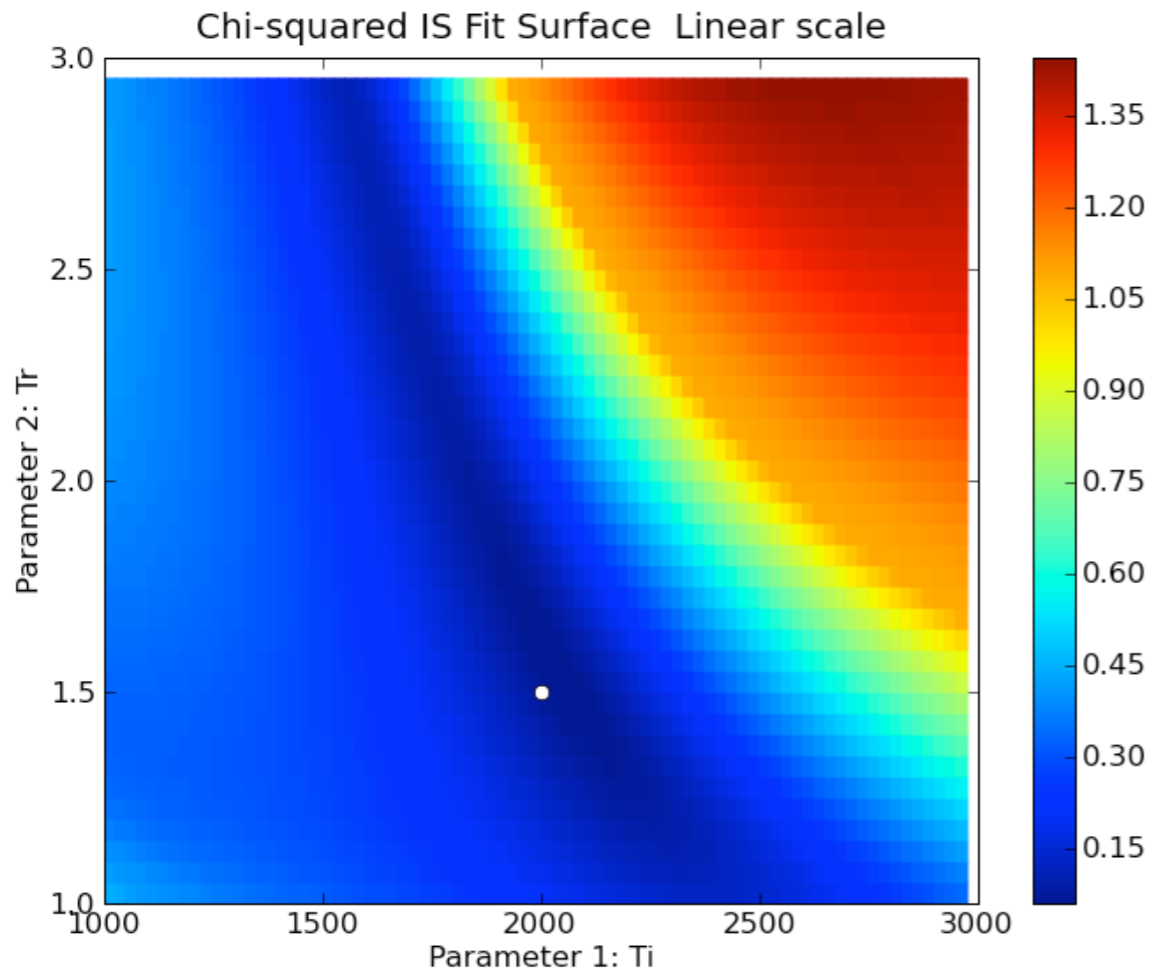


440 MHz IS Spectrum  
 Ti/Tr space  
 Ti = 2000 Tr = 1.5  
 Poor sampling





440 MHz IS Spectrum  
 Ti/Tr space  
 Ti = 2000 Tr = 1.5  
 Noisy



440 MHz IS Spectrum  
 Ti/Tr space  
 Ti = 2000 Tr = 1.5  
 Noisy, poor sampling

# Eigenvalues of Hessian matrix (2nd derivative of min fn) has insights on parameter ambiguities

Table 5.1: Fit results and uncertainty values at 923 km for conditions over Arecibo at 20:41 LT on January 14, 1991. The most ill-defined parameter vector is found from the Hessian matrix eigenvector with the smallest eigenvalue.

### Fitter results:

	Best-fit results	Uncertainty
$N_e$	$6.41 \times 10^4$	$7.39 \times 10^3$
$T_e$	2285	41.3
$T_i$	2223	23.4
$f_{H^+}$	0.490	0.00483
$f_{He^+}$	0.159	0.00341

### Correlations between pairs of parameters:

Param Pair	Correlation	Param Pair	Correlation
$[N_e, T_e]$	0.958	$[T_e, f_{H^+}]$	-0.916
$[N_e, T_i]$	-0.649	$[T_e, f_{He^+}]$	-0.401
$[N_e, f_{H^+}]$	-0.849	$[T_i, f_{H^+}]$	0.414
$[N_e, f_{He^+}]$	-0.511	$[T_i, f_{He^+}]$	0.515
$[T_e, T_i]$	-0.440	$[f_{H^+}, f_{He^+}]$	0.099

### Most ill-defined parameter combination:

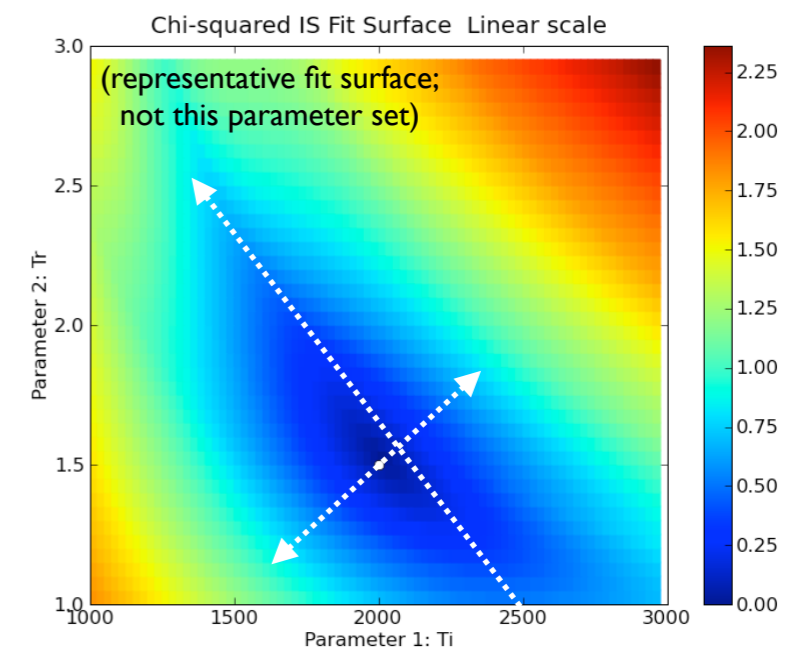
$$+0.998 (N_e) + 0.0527 (T_e) - 0.0202 (T_i) + 5.46 \times 10^{-6} (f_{H^+}) - 2.32 \times 10^{-6} (f_{He^+})$$

$$\hat{\beta}_{LS} = \min_{\beta} \sum_i \frac{[h_i(\beta) - Z_i]^2}{\sigma_i^2}$$

$$\text{Cov} \{ \hat{\beta}_{LS} \} \approx [ \tilde{J}^T \tilde{J} ]^{-1}$$

$$\tilde{J} = \begin{pmatrix} \frac{1}{\sigma_0} \frac{\partial h_0}{\partial \beta_0} & \frac{1}{\sigma_0} \frac{\partial h_0}{\partial \beta_1} & \cdots & \frac{1}{\sigma_0} \frac{\partial h_0}{\partial \beta_{M-1}} \\ \frac{1}{\sigma_1} \frac{\partial h_1}{\partial \beta_0} & \frac{1}{\sigma_1} \frac{\partial h_1}{\partial \beta_1} & \cdots & \frac{1}{\sigma_1} \frac{\partial h_1}{\partial \beta_{M-1}} \\ \vdots & \vdots & \vdots & \vdots \\ \frac{1}{\sigma_{N-1}} \frac{\partial h_{N-1}}{\partial \beta_0} & \frac{1}{\sigma_{N-1}} \frac{\partial h_{N-1}}{\partial \beta_1} & \cdots & \frac{1}{\sigma_{N-1}} \frac{\partial h_{N-1}}{\partial \beta_{M-1}} \end{pmatrix}$$

Eigenvalues of  $[ \tilde{J}^T \tilde{J} ]$



# Improving the fit: adding priori constraints

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Bayesian statistics: add apriori knowledge to stabilize fit.

Can come from other instruments, or from data at other altitudes/times.

One formulation: minimize

$$\chi^2 = \chi_{data}^2 + \chi_{apriori}^2$$

Here, the apriori information adds a cost for solutions which wander too far from the apriori knowledge. (DANGER!)

Many implementations in our field:

Constrained temperature profiles

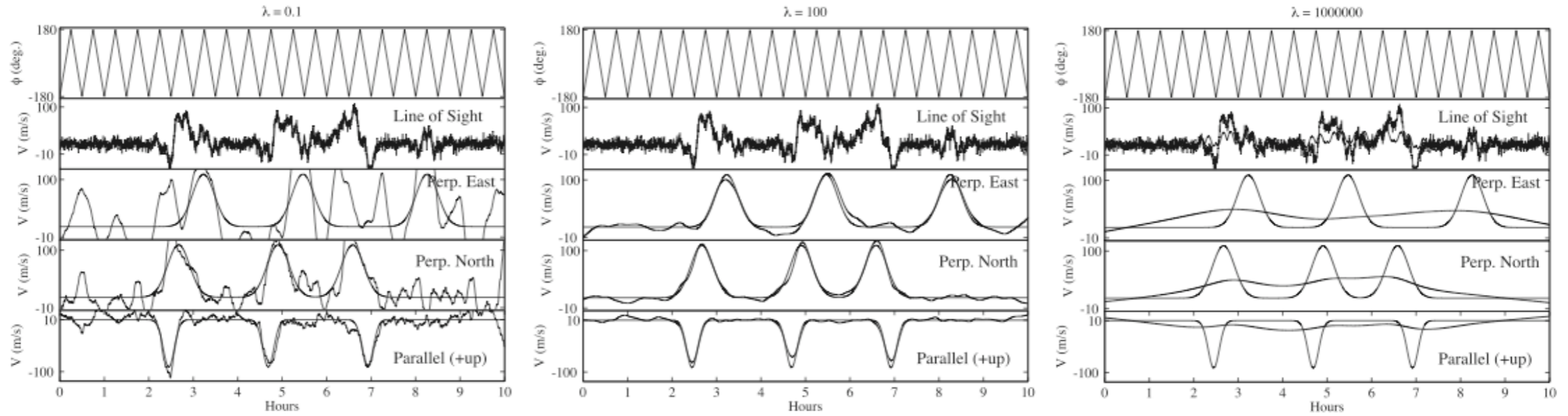
Vector velocity fits

Full profile analysis

Regularization

Etc.

(techniques such as Tikhonov regularization used to set relative weight of data and apriori terms when minimizing)



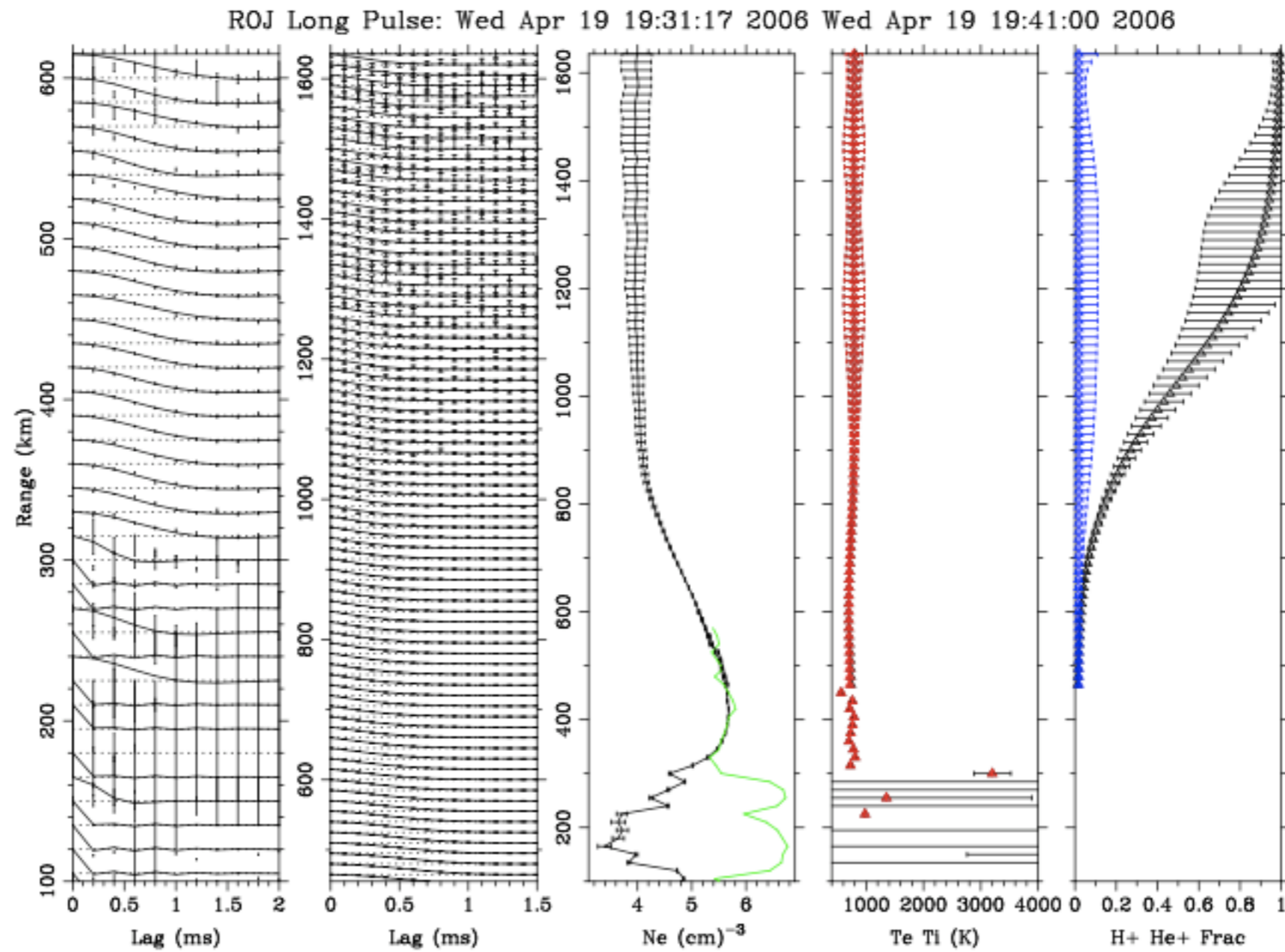
**Figure 3.** Vector velocity input-output comparison using a simulation assuming a single beam and applying the method of regularization. The panels on the left show the results for a small value of  $\lambda$ . The panels on the center were obtained from a simulation with an optimal value of  $\lambda$ , while the panels on the right correspond to a case with too much  $\lambda$ .

$$\begin{bmatrix} V_{pn} \\ V_{pe} \\ V_{par} \end{bmatrix} = \begin{bmatrix} -\cos \delta \sin I & \sin \delta \sin I & \cos I \\ \sin \delta & \cos \delta & 0 \\ \cos \delta \cos I & -\sin \delta \cos I & \sin I \end{bmatrix} \begin{bmatrix} v_x \\ v_y \\ v_z \end{bmatrix}.$$

$$\begin{bmatrix} V_{LOS(1)} \\ \vdots \\ V_{LOS(n)} \end{bmatrix} = \begin{bmatrix} -\cos \phi_1 \sin \theta & \sin \phi_1 \sin \theta & \cos \theta \\ \vdots & \vdots & \vdots \\ -\cos \phi_n \sin \theta & \sin \phi_n \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} v_x \\ v_y \\ v_z \end{bmatrix}$$

Arecibo linear regularization of line-of-sight velocities for full vector derivation

Sulzer et al, 2005



**Fig. 3.** Jicamarca profiles for 19:30 LT (00:30 UT). From left to right, the panels represent double-pulse lag products, long-pulse lag products, electron density, electron and ion temperature, and light ion fraction (see text).

Full profile at JRO Hysell et al, 2008  
6 cost functions inject weighted apriori information

# IS Fitting Examples, Ambiguities, and Constrained Analysis

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## Summary:

- Fitting forward model to data yields estimates of model parameters
- Many models (including incoherent scatter) can have more than one parameter solution that fits data
- Regularization or constraints can help select a final solution when carefully applied
- Consult your local friendly Geospace Facility scientist for advice