

Use this to play around and brainstorm how we want to organize and outline the Engineering report, rather than playing around on LaTeX w/ Overleaf.

## 1 Introduction

- Hamstring Injury in NFL
- Current Methods for Rehabilitation (GHD exercises)
- Current method to analyze rehabilitation (i.e Nordbord)
- Limitations of nordbord (difficulty, size restraints, seperate machine that does not represent rehab training)
- Purpose of project
  - Incorporate versatility of GHD with sensing capabilities of NordBord

## 2 Methodology

### 2.1 Overall Plan

- Develop of method to measure the force output of the hamstrings during various exercises on the GHD. This includes
  - integrating force sensors onto the ankle rests of the GHD
  - Modeling the human body on the GHD for a variety of positions and movements
  - Coverting the measured external force into internal force
  - Providing a user friendly interface to observe and compare the produced data

### 2.2 Sensors

- Researched different types of force sensors to determine which is the best for measuring ankle reaction force
  - Looked into piezoelectric sensors, load cells, and pressure pads
  - Criteria for selection involved testing for repeatability, ability to physically integrate, price, force capacity, and NordBord method of force measurement
- Designed and built multiple test setups to determine the optimal locations for the load cells
  - Informed designs of test setups with GHD ankle supports
- Process the raw data into a more accessible format (excel)
  - Convert voltage readings from an arduino to lbs or newtons in an excel sheet

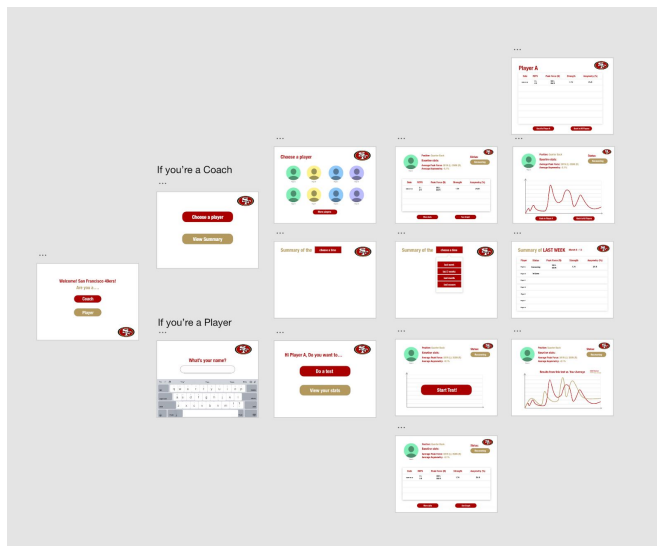
### 2.3 Biomech Model

- Explanation of model and variables

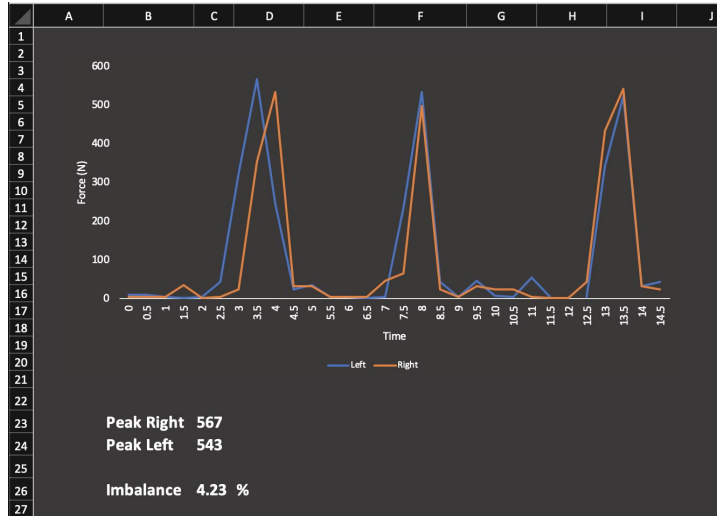
- Walk through of the input to the model, and how we get the output (internal forces)
- See overleaf (mostly complete already)

## 2.4 UI

- Designed a user interface that is able to use data from the strength test sensors and biomech sub-teams using wireframing techniques on Sketch and Adobe XD
  - Takes in in input from sensors, coaches/trainers, athletes (strain gauge data, goals from trainers)
    - Inputs defined by 49ers coaches and biomech sub team
  - Outputs force exerted by both left and right legs over time, peak force and asymmetry
- Created wireframes for:
  - Trainers to input relevant information needed for an athlete and test they want to perform
  - Athletes to perform the exercise
  - Trainers to receive appropriate test information
  - Initial designs:



- Experimented with Excel macro scripts and MATLAB code to export data from MATLAB and immediately plot in Excel with a clear and streamlined User Interface



- Presented design iterations to 49ers coaches and took their feedback into account
  - Main feedback:
    - The player should have as little access to information as possible
    - Should only see the test they are currently taking and then be able to submit it
    - Trainers should be able to see more information like player recovery status and the player's trend over time
  - Implemented this feedback and continued to iterate

### 3 Results and discussion

#### 3.1 Sensors

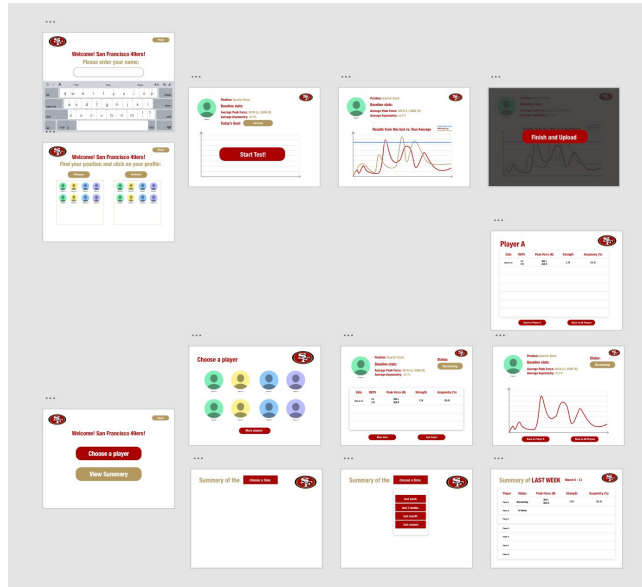
- Determined that a load cell is the best way to go for force measurement
  - Pulling force measurement is more reliable than contact force
  - We were unable to compare detailed effectiveness of specific test setups, but believe that the general direction of test setup is correct
- Example raw data and explanation

#### 3.2 Biomechanical Model

- Show intermediate and final output data of the model. For example, for the given example raw data from sensors, show how the model predicts the knee angle for a given ankle force, and then show the output (Hamstring Force, Joint Force, Knee Angle)

#### 3.3 UI

- Polished wireframe including use cases for a trainer/coach to set goals for players and see their test results and status and for a player to conduct a test



- Integration with the biomech and sensor teams to take in data from the sensors and perform calculations on them and then plot the information in excel

#### 4. Conclusions and Future work

- Integrate sensors and software into a GHD machine to have both the adaptability of the GHD with the force sensing capability of our work