



Radar 2: basic signal processing and radar coding

Ilkka Virtanen
Ionospheric Physics research unit
University of Oulu, Finland



Outline

- **Some useful mathematics**
- **Baseband signal**
- **Working principle of a pulsed radar**
- **Range-time diagram**
- **Range and Doppler aliasing**
- **Underspread and overspread targets**
- **Radar coding**



Mathematical tools

– Euler's identity

- $e^{i\phi} = \cos \phi + i \sin \phi$

– Generic signal with amplitude and phase modulation

- $z(t) = A(t)e^{i(\omega_0 t + \phi(t))}$

– Fourier transform

- $Z(\nu) = \mathcal{F}\{z(t)\} = \int_{-\infty}^{\infty} z(t)e^{-i\omega t} dt$

- $z(t) = \mathcal{F}^{-1}\{Z(\nu)\} = \int_{-\infty}^{\infty} Z(\nu)e^{i\omega t} d\nu$

- $\omega = 2\pi\nu$

– Convolution

- $f(t) * g(t) = \int_{-\infty}^{\infty} f(\tau)g(t - \tau)d\tau$

- $\mathcal{F}\{f(t) * g(t)\} = F(\nu)G(\nu)$

– Correlation

- $f(t) \circ g(t) = \int_{-\infty}^{\infty} f^*(\tau)g(\tau + t)d\tau$

- $\mathcal{F}\{f(t) \circ g(t)\} = F^*(\nu)G(\nu)$

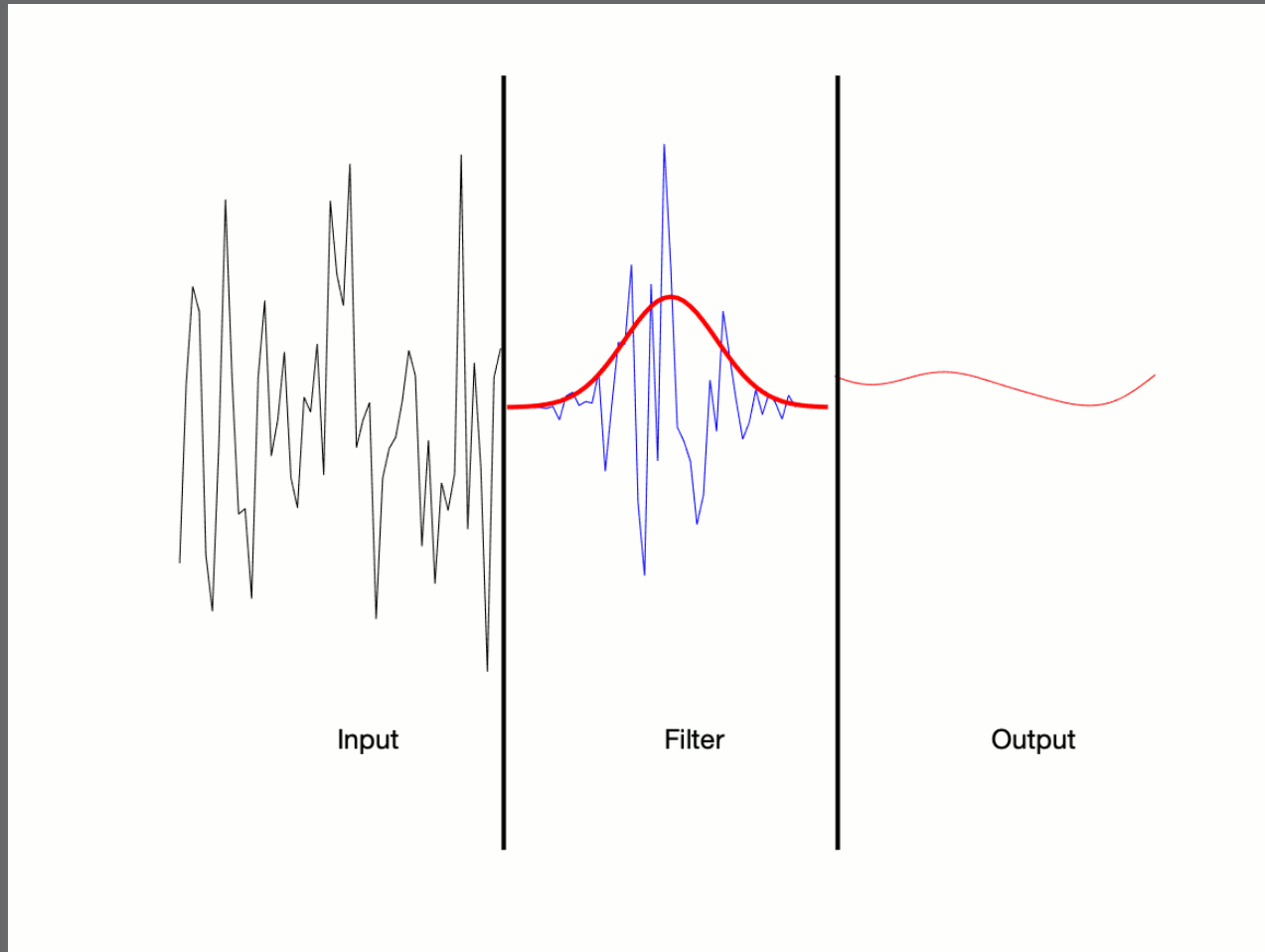
– Autocorrelation

- $f(t) \circ f(t) = f(t) * f^*(-t)$

- $\mathcal{F}\{f(t) \circ f(t)\} = |F(\nu)|^2$



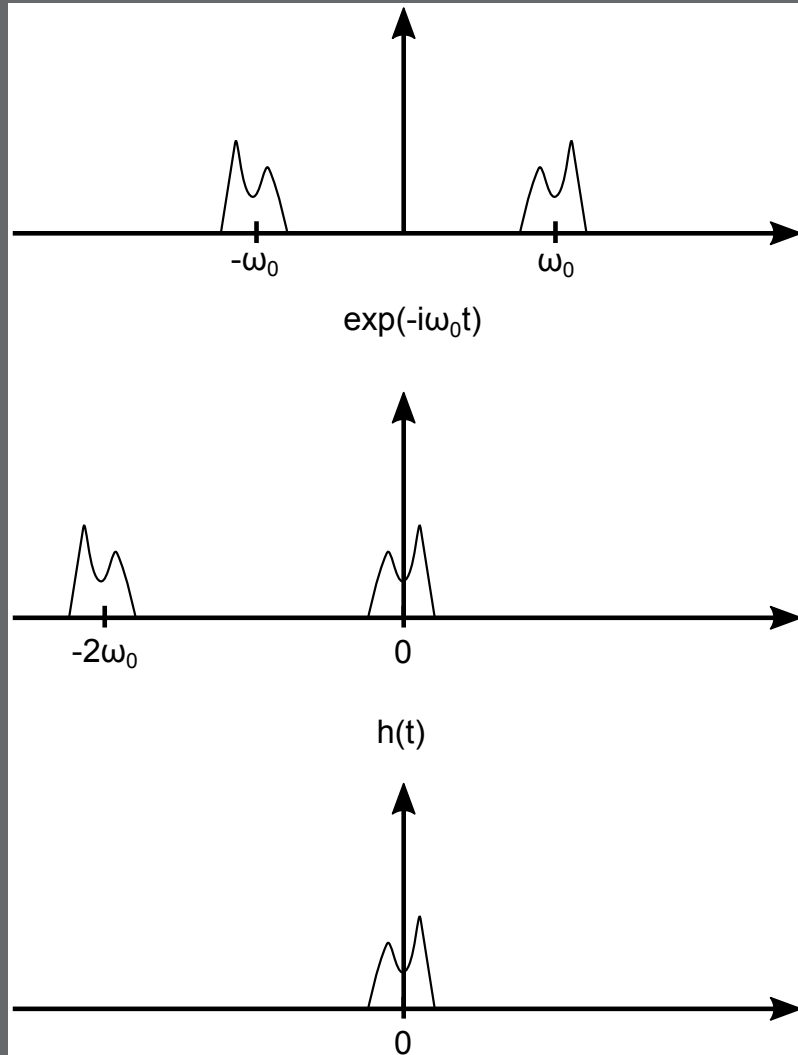
The convolution integral and filtering



- A linear filter has an impulse response $h(t)$
- When the filter input signal is $z_i(t)$, the output signal $z_o(t)$ is the convolution
$$z_o(t) = h(t) * z_i(t) = \int_{-\infty}^{\infty} h(\tau) z_i(t - \tau) d\tau$$



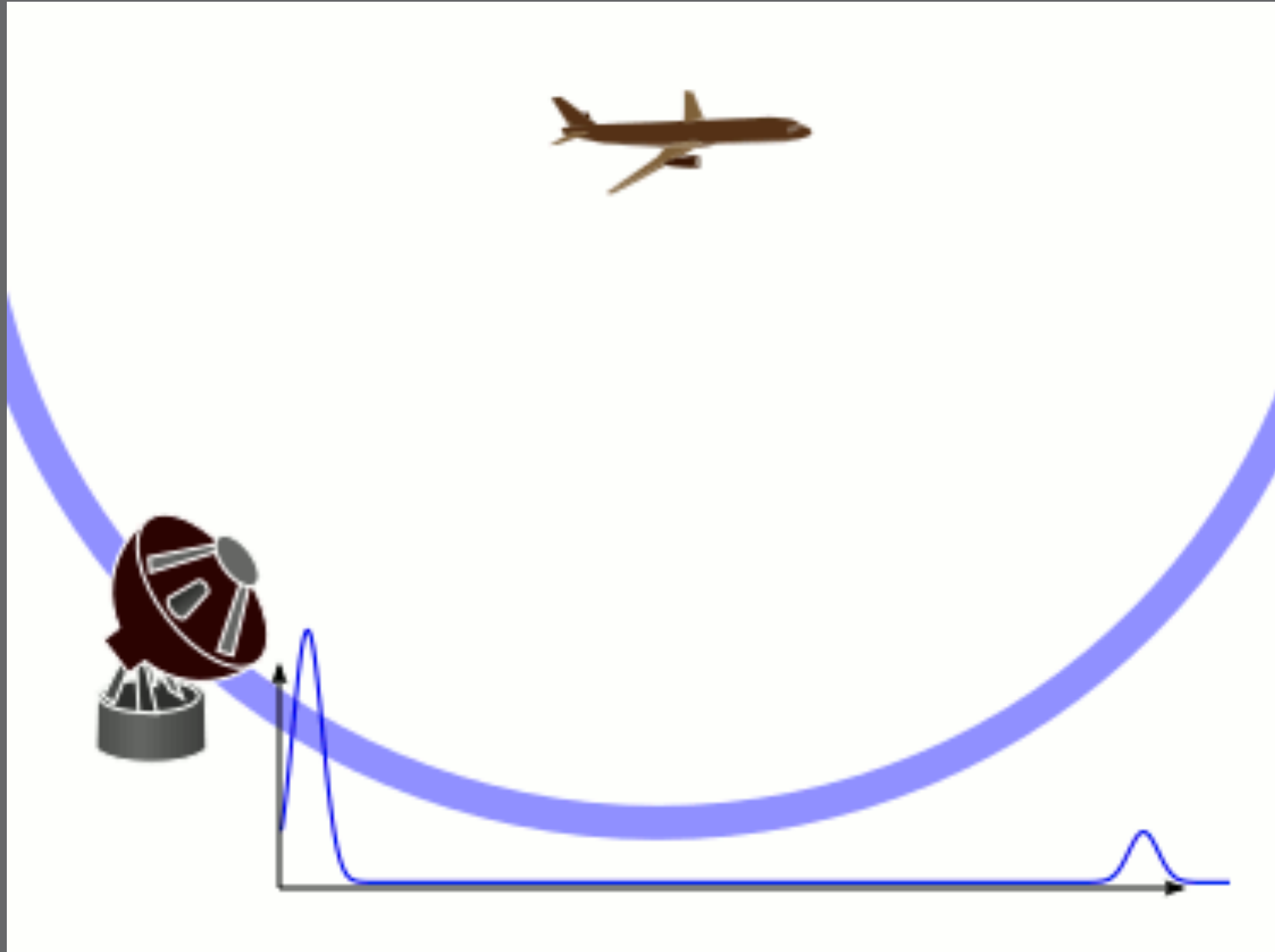
Baseband signal



- Spectrum of the original signal $z(t)$ is centered around ω_0 and $-\omega_0$
- Multiplication with $e^{-i\omega_0 t}$ shifts both spectrum peaks by $-\omega_0$
- When the shifted signal is filtered with a sufficient filter $h(t)$, the peak centered around $-\omega_0$ is removed
- Nyquist sampling theorem:
 - A signal with cut-off frequency f_m can be perfectly reconstructed from samples taken at frequency f_s if $f_s \geq 2f_m$

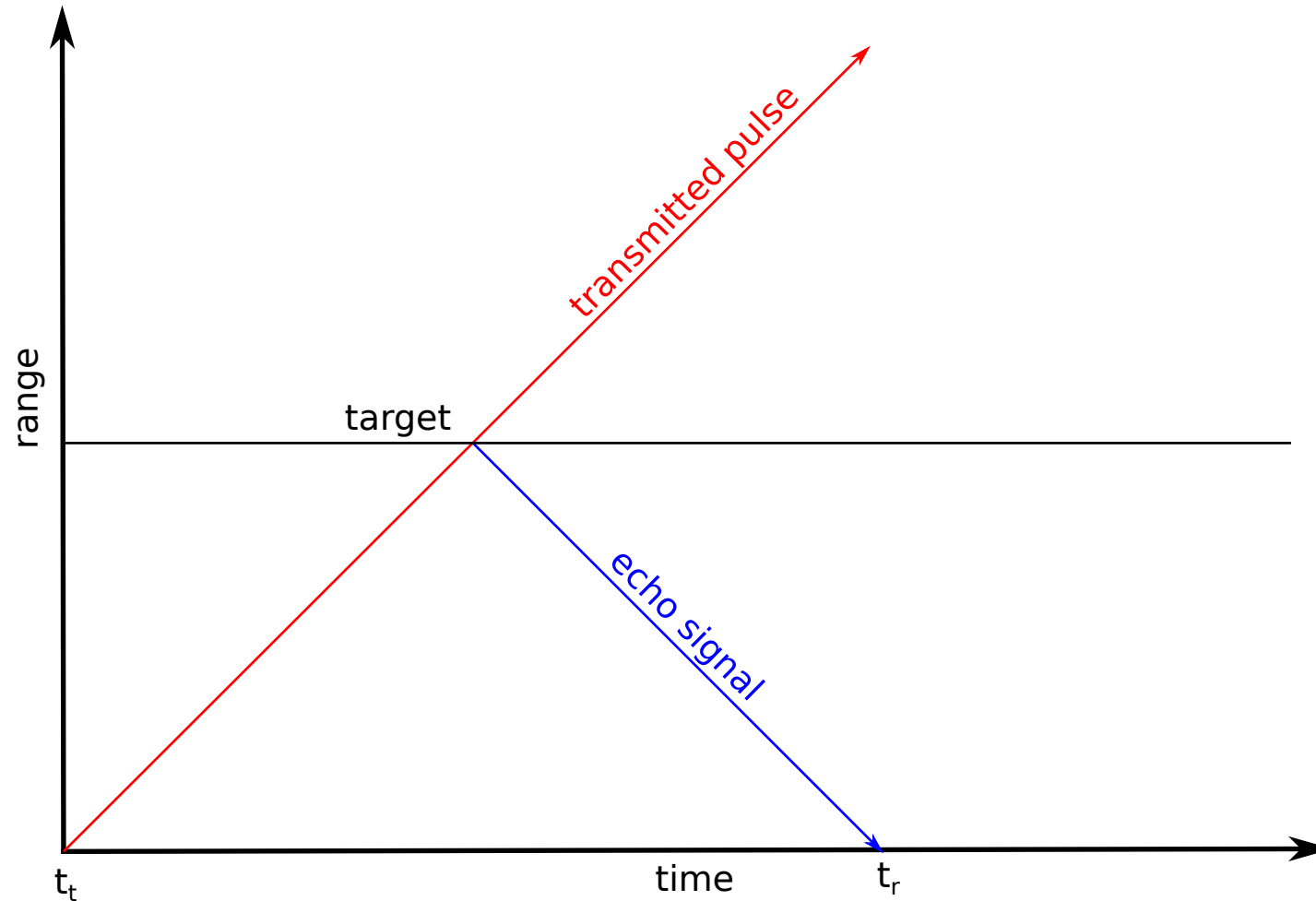


Radar



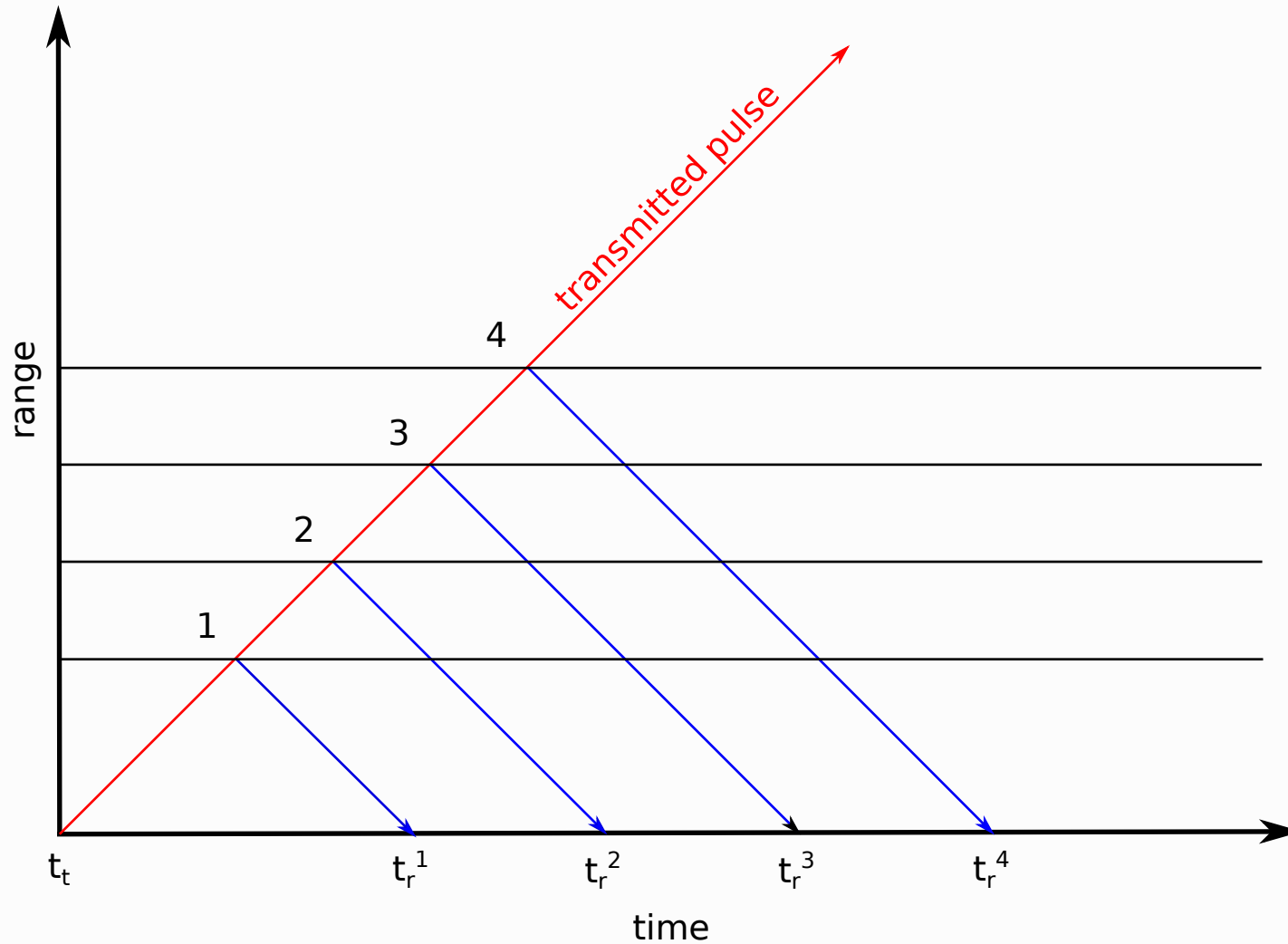


Range-time diagram

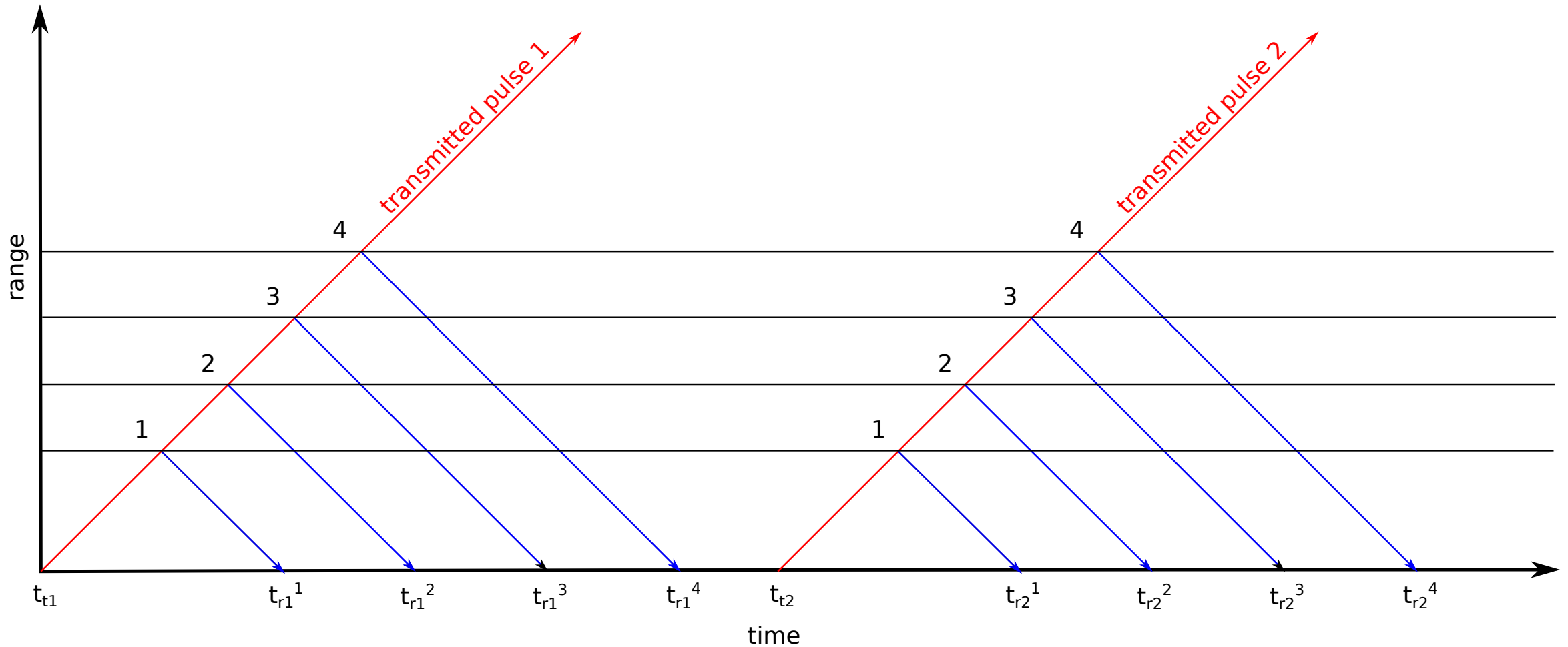




Range-time diagram: 1 short pulse, 4 targets

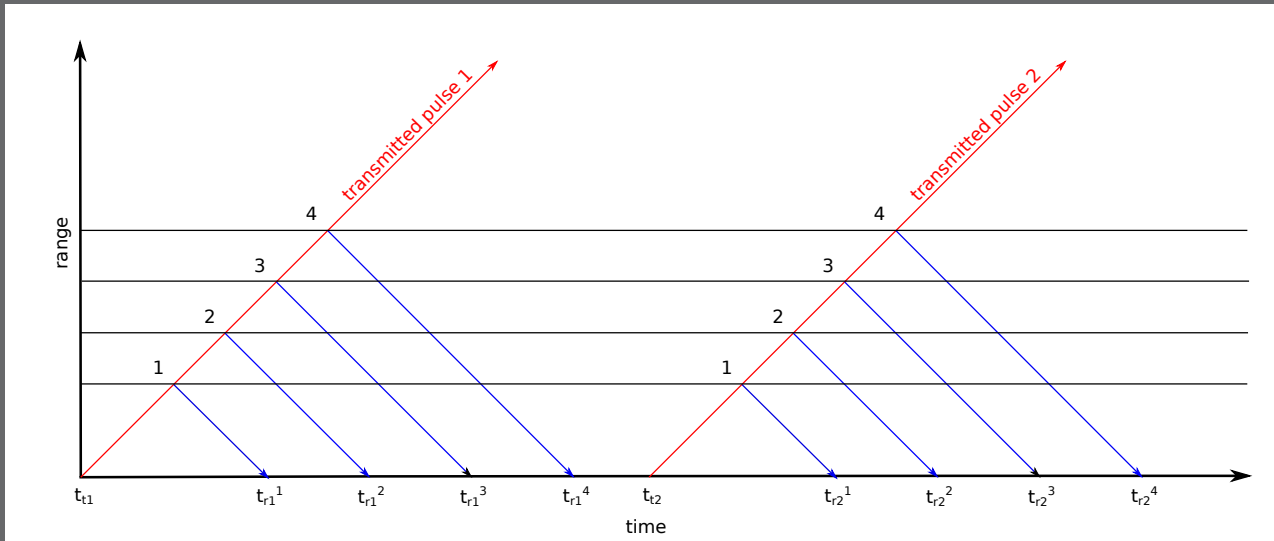


Range-time diagram: multiple short pulses, 4 targets





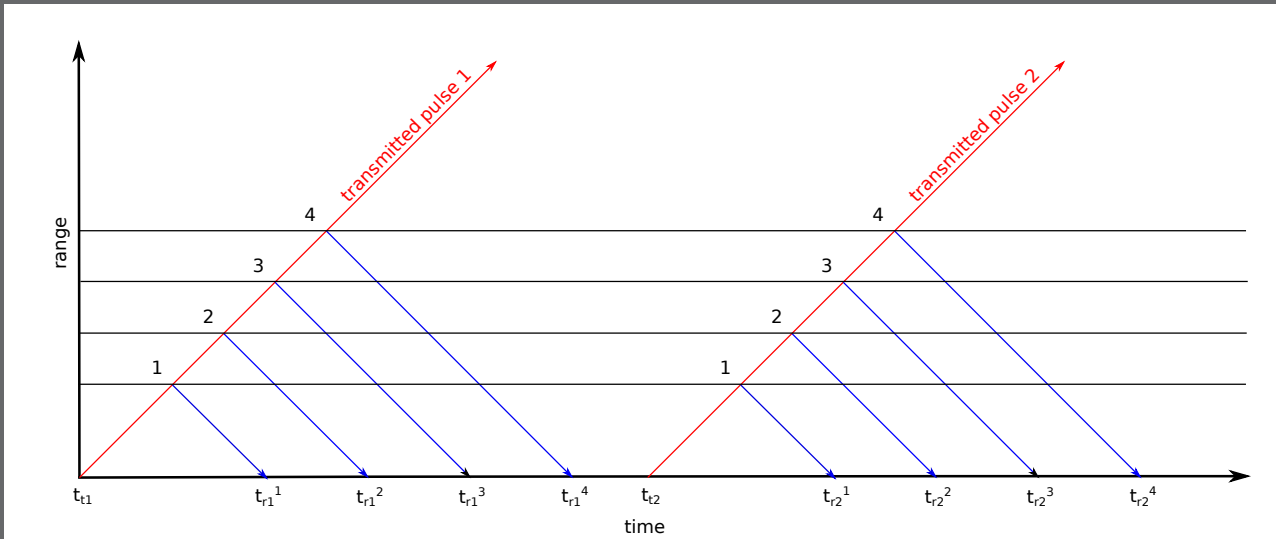
Simple spectrum estimation



- Short pulses transmitted at regular intervals $\Delta t_t = t_{t2} - t_{t1}$
- We get one echo sample per pulse from each altitude
- Sampling frequency $f_s = 1/\Delta t_t$
- Nyquist sampling theorem:
 - A signal with cut-off frequency f_m can be perfectly reconstructed from samples taken at frequency f_s if $f_s \geq 2f_m$



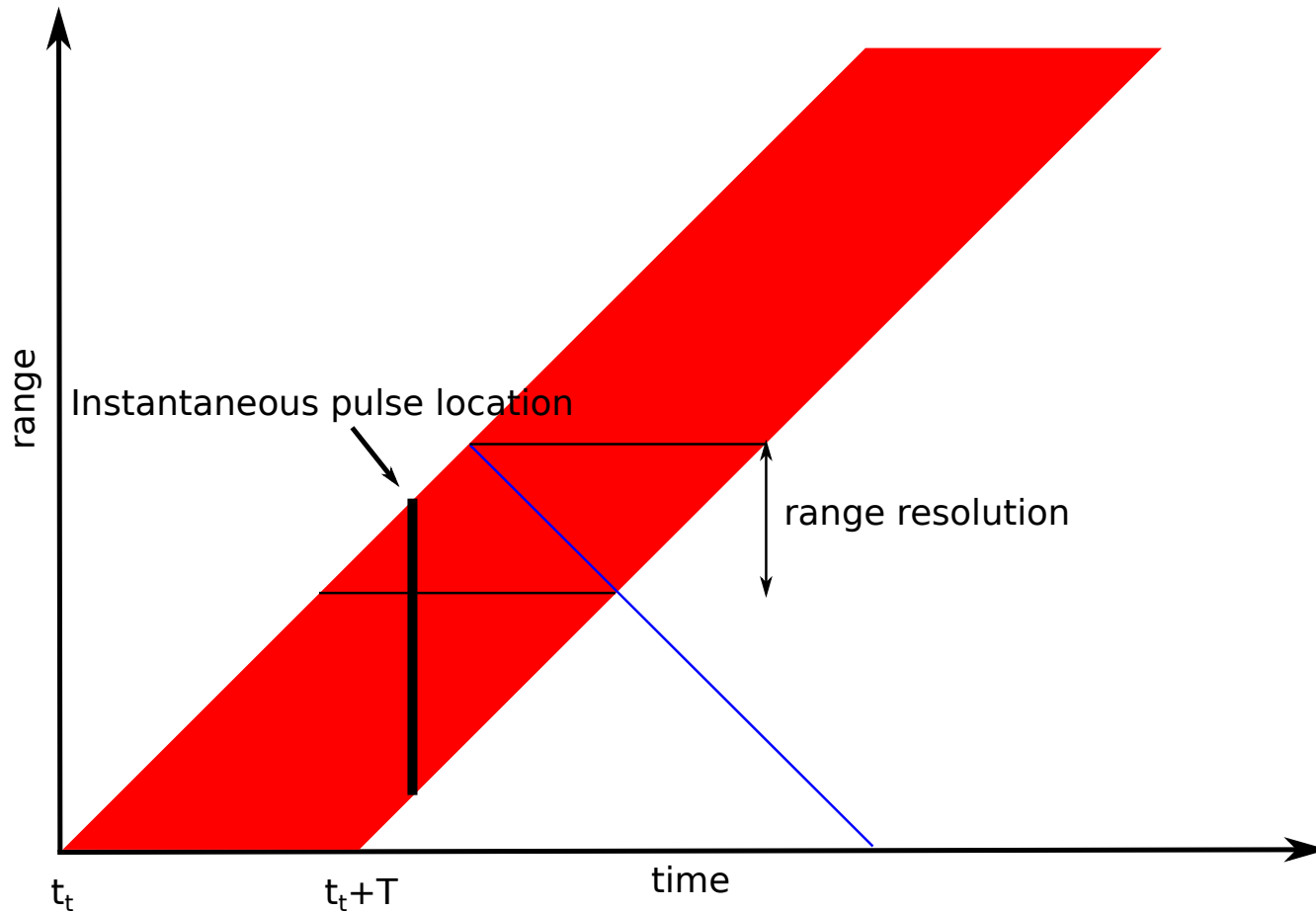
Underspread vs overspread target



- Signal roundtrip time $S = \frac{2R}{c}$
- Width of the target spectrum Δf
- Underspread target: $\Delta f < \frac{1}{S}$
- The target spectrum can be estimated using echo samples from subsequent transmitted pulses (pulse-to-pulse correlations)
- Overspread target: $\Delta f > \frac{1}{S}$
- We must collect several echo samples from each range per pulse (intra-pulse correlations)



Pulse length vs range resolution

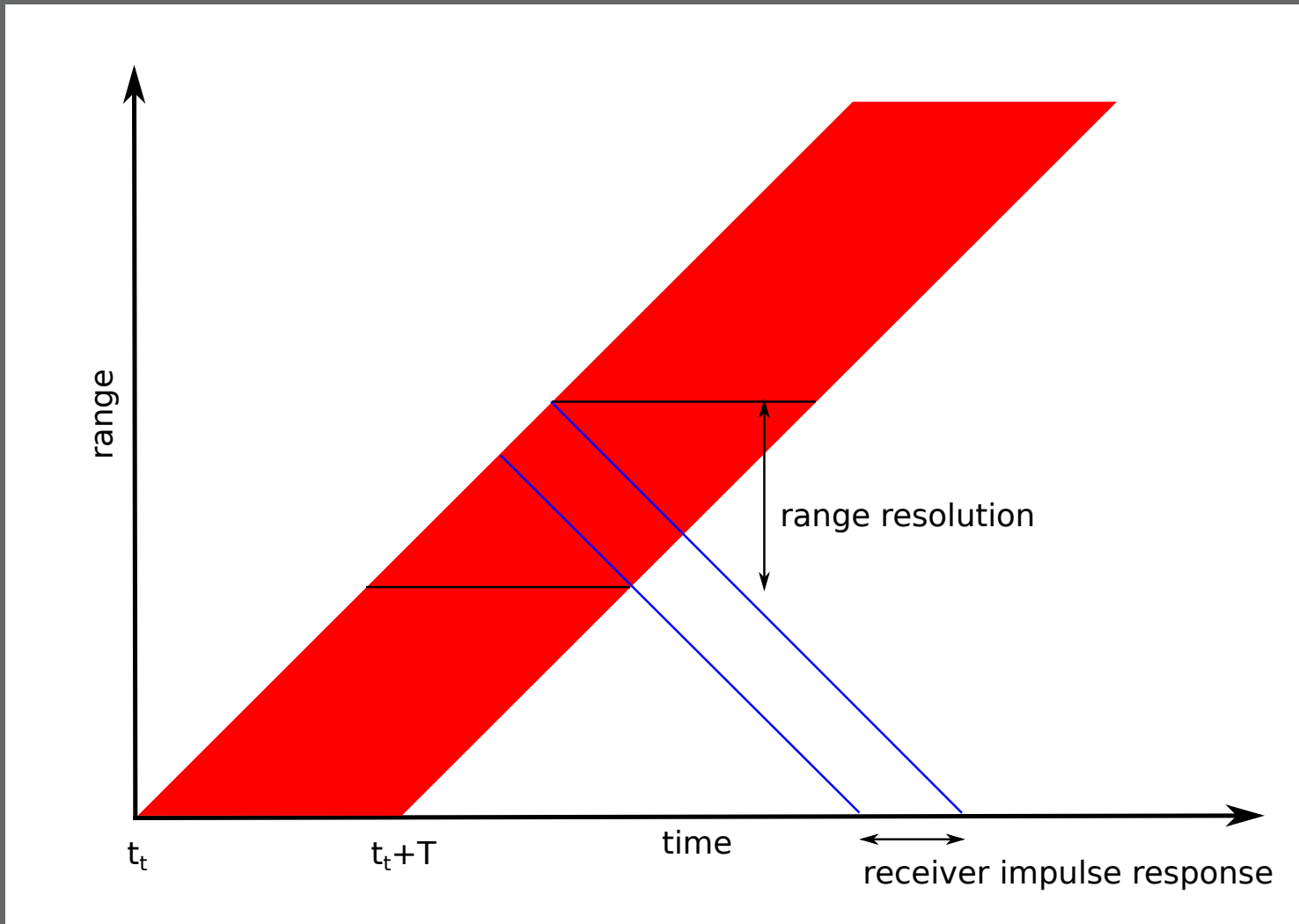


- Echo from a pulse of duration T come from a volume whos length is

$$\Delta S = \frac{c}{2} T$$



Pulse length vs range resolution



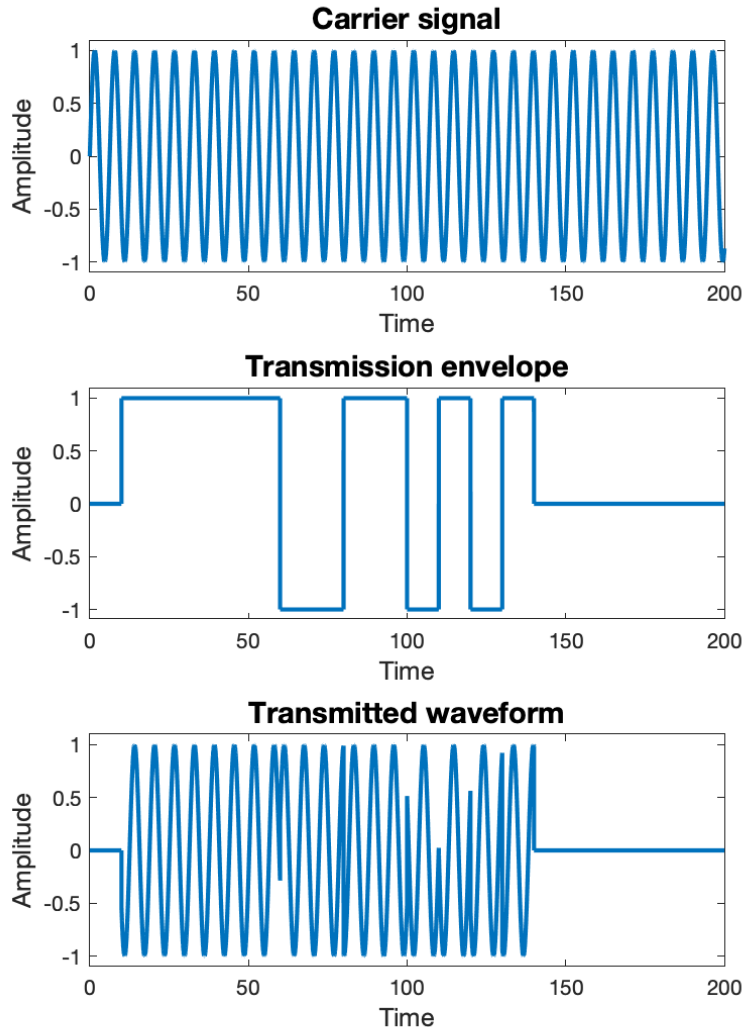
- In reality, the received signal $z_r(t)$ is a convolution of the echo signal $z(t)$ and the receiver impulse response $h(t)$

$$z_r(t) = \int_{-\infty}^{\infty} h(\tau)z(t - \tau)d\tau$$

- The final range resolution is
$$\Delta S_r = \frac{c}{2} (T + T_h),$$
 where T_h is length of the receiver impulse response



Transmission modulation (radar coding)

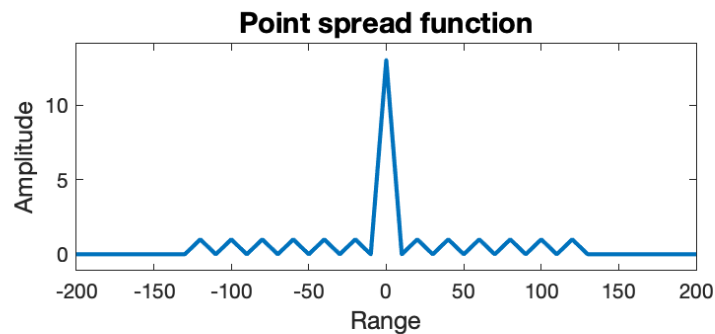
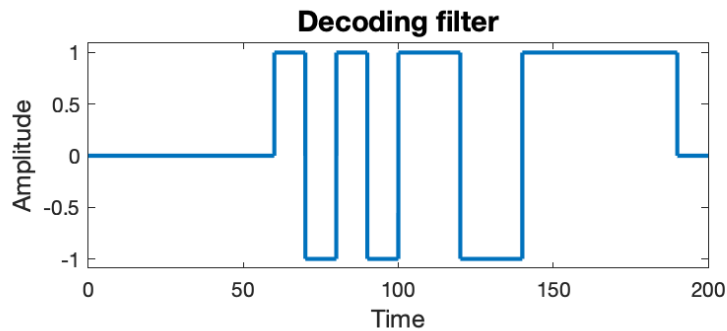
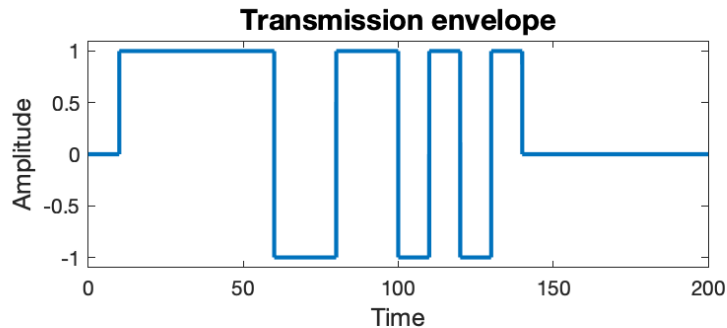


- Long pulses, which correspond to short pulses with higher peak power after decoding
- Carrier signal $z_c(t) = A_c e^{i\omega_c t}$
- Transmission envelope $z_e(t) = A_e(t) e^{i\phi_e(t)}$
- Transmitted waveform $z_t(t) = z_c(t) z_e(t)$

- Binary coding
 - $A_e(t) = \begin{cases} 1, & \text{when } 0 < t < T_{pulse} \\ 0, & \text{otherwise} \end{cases}$
 - $\phi_e(t) \in [0, \pi]$
- From this point on, we will use baseband signals and ignore the carrier frequency



Pulse compression, coherent target



- **Single target at distance r**

- Signal roundtrip time $S = \frac{2r}{c}$

- Received echo signal $z_r(t) = A_s z_e(t - S)$

- The complex constant A_s absorbs the effects of distance, radar cross-section and Doppler shift

- **Matched filter decoding**

- Convolve the received signal with the decoding filter

$$z_d(t) = z_e^*(-t)$$

- Decoding filter output

$$z_m(t) = \int_{-\infty}^{\infty} z_r(\tau) z_d(t - \tau) d\tau$$

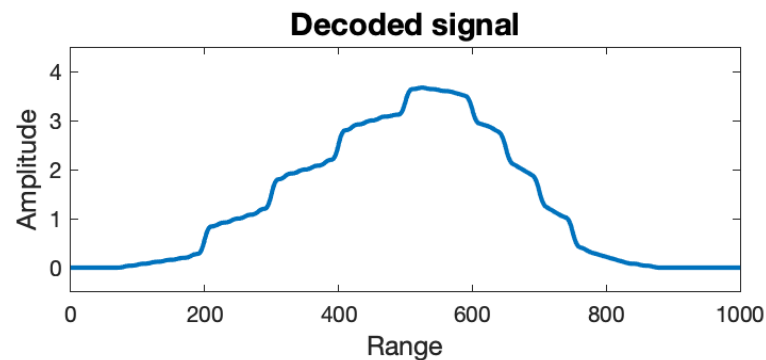
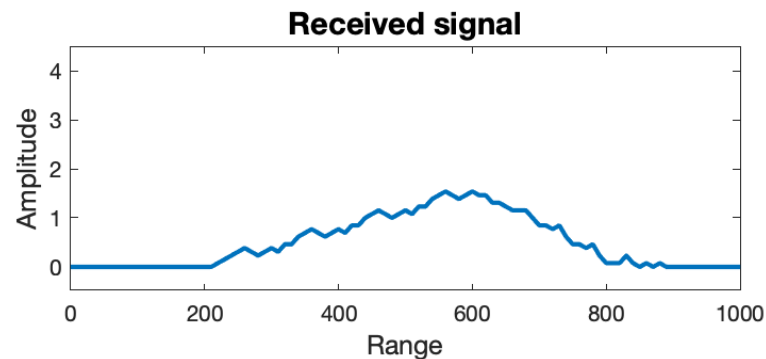
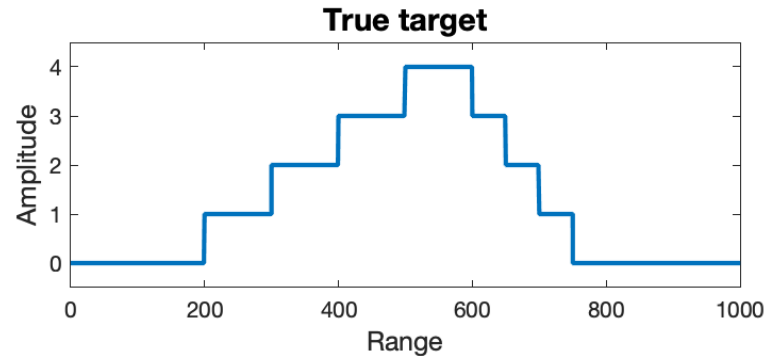
$$= A_c A_s \int_{-\infty}^{\infty} z_e(\tau - S) z_e^*(t + \tau) d\tau = A_c A_s \mathcal{R}_{z_e}(t - S)$$

- $\mathcal{R}_{z_e}(t - S)$ is the autocorrelation function of the transmission envelope z_e (point spread function)





Range-spread target



- When the target is not point-like, we get scattering from all ranges. The received signal is a convolution of the transmitted waveform and the target

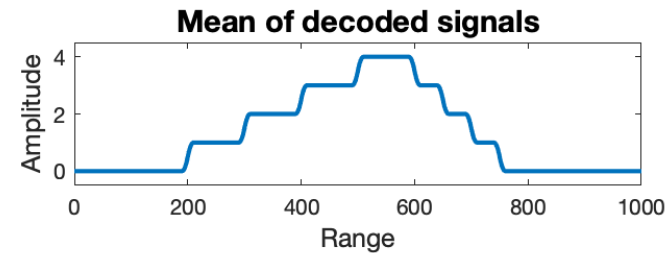
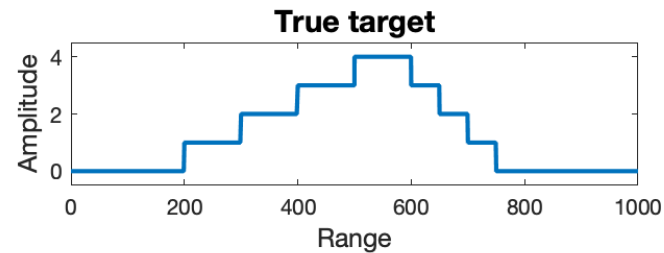
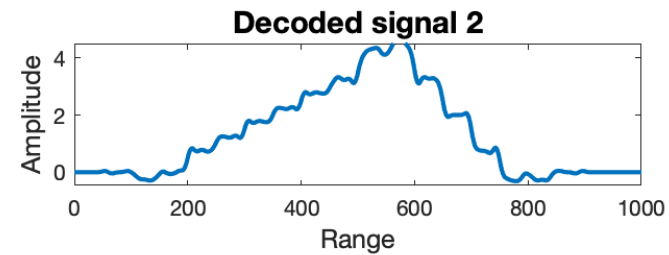
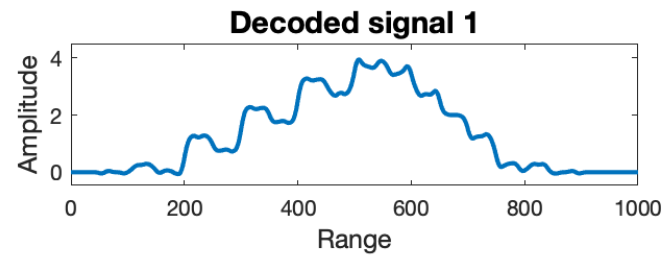
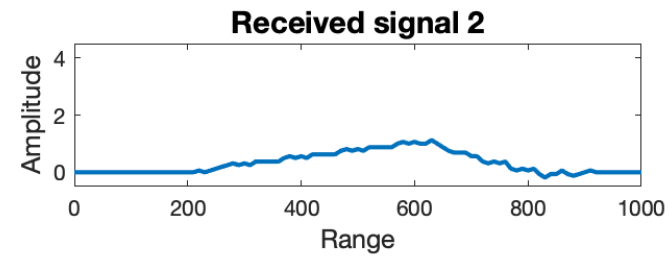
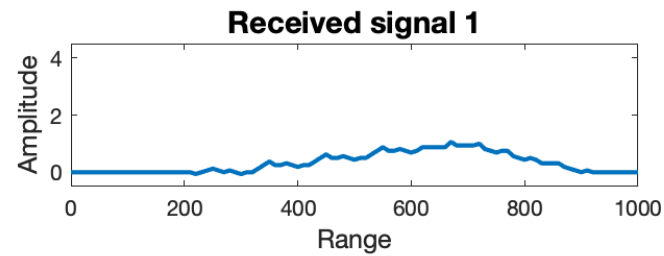
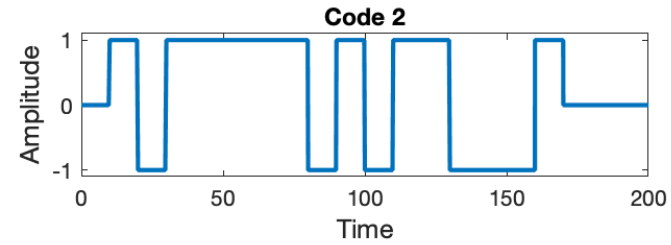
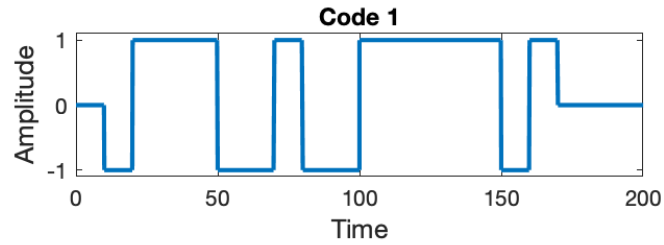
$$z_r(t) = \int A_s(S)z_e(t - S) dS$$

- The decoded signal is a convolution of the target and the point spread function

$$z_m(t) = A_c \int A_s(S)\mathcal{R}_{z_e}(t - S) dS$$

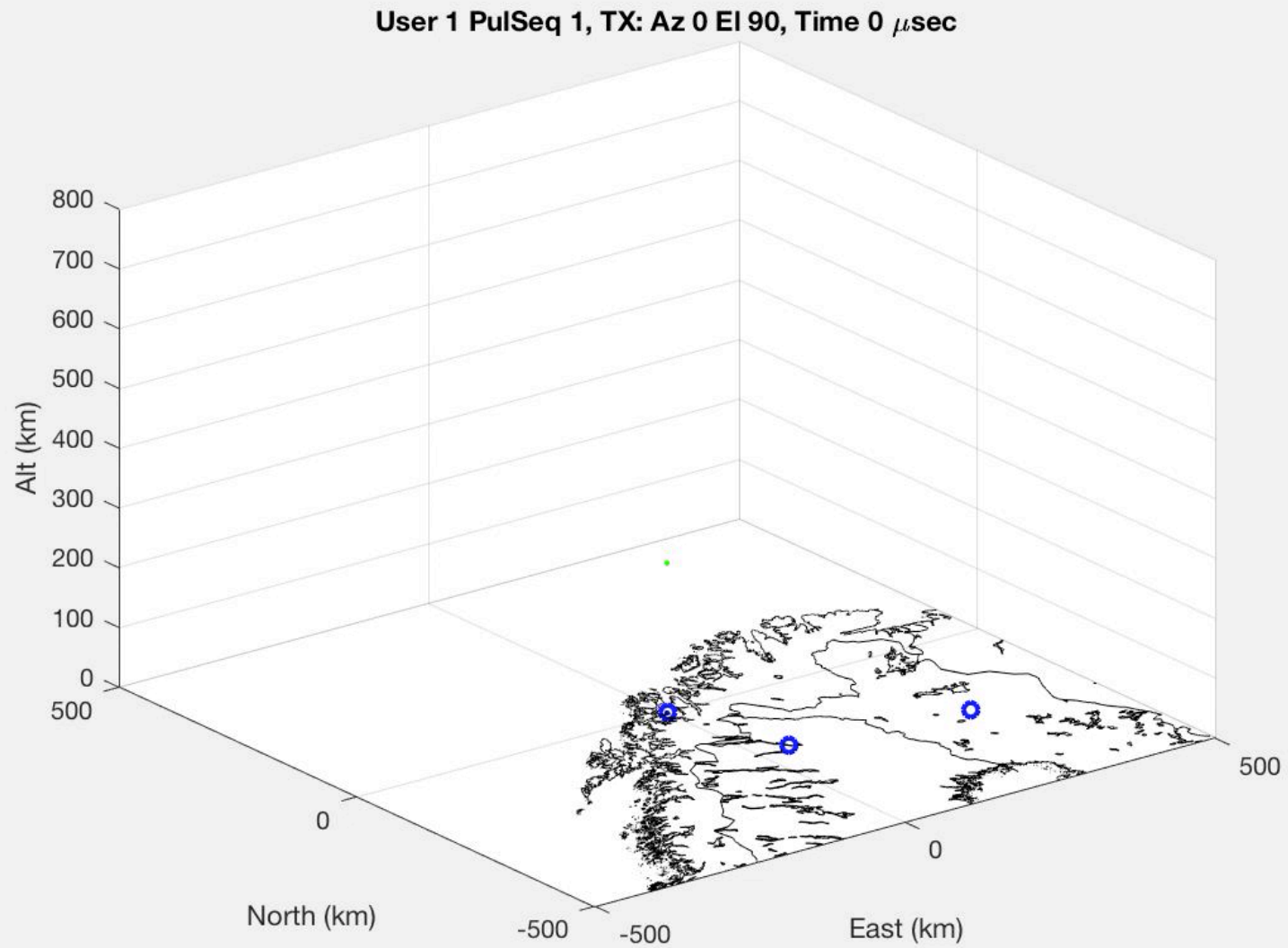


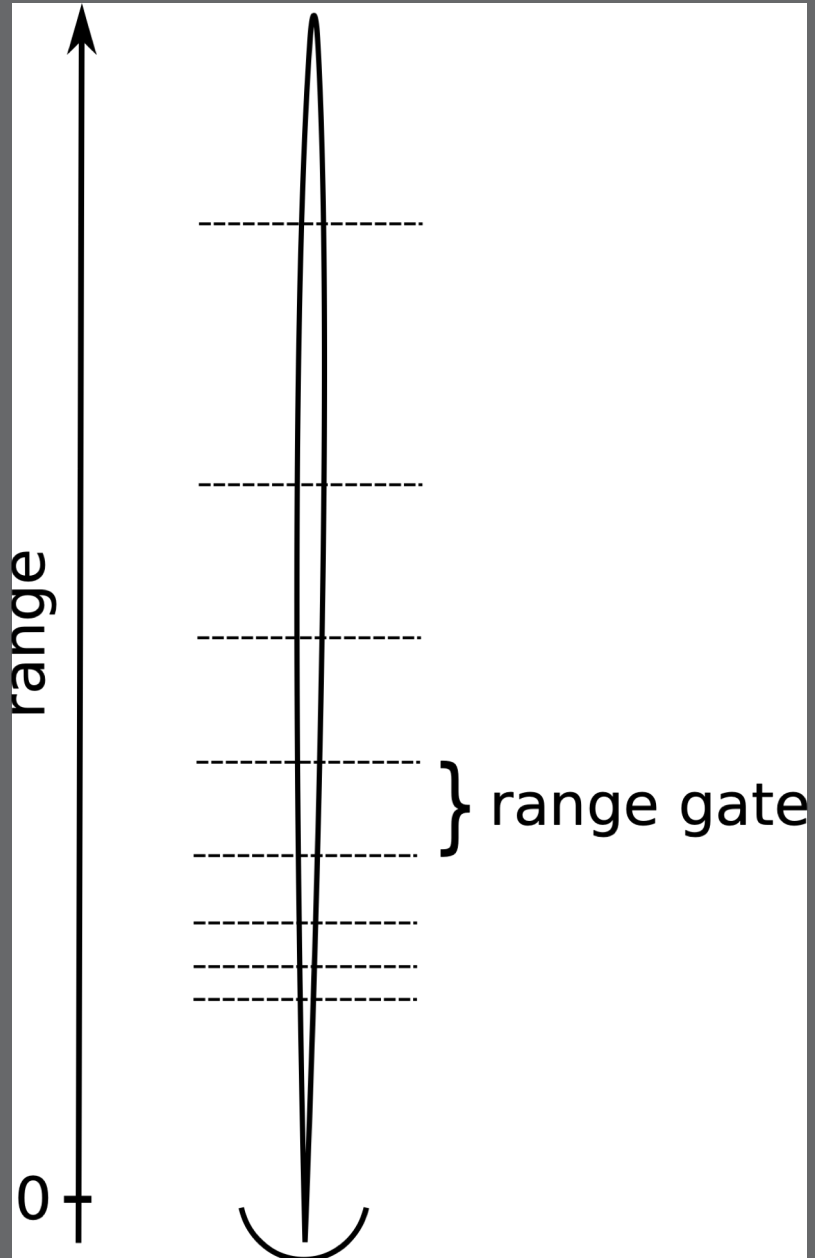
Complementary codes





EISCAT radar



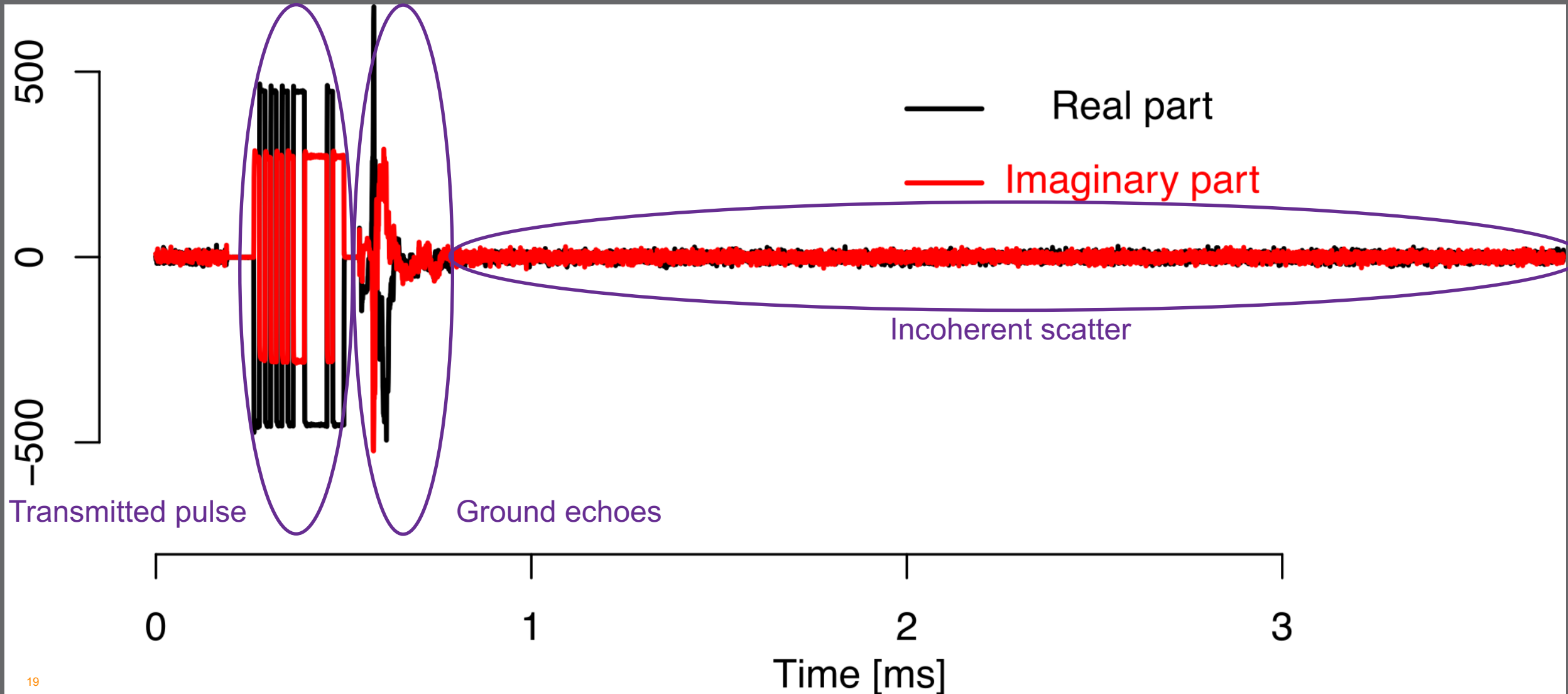


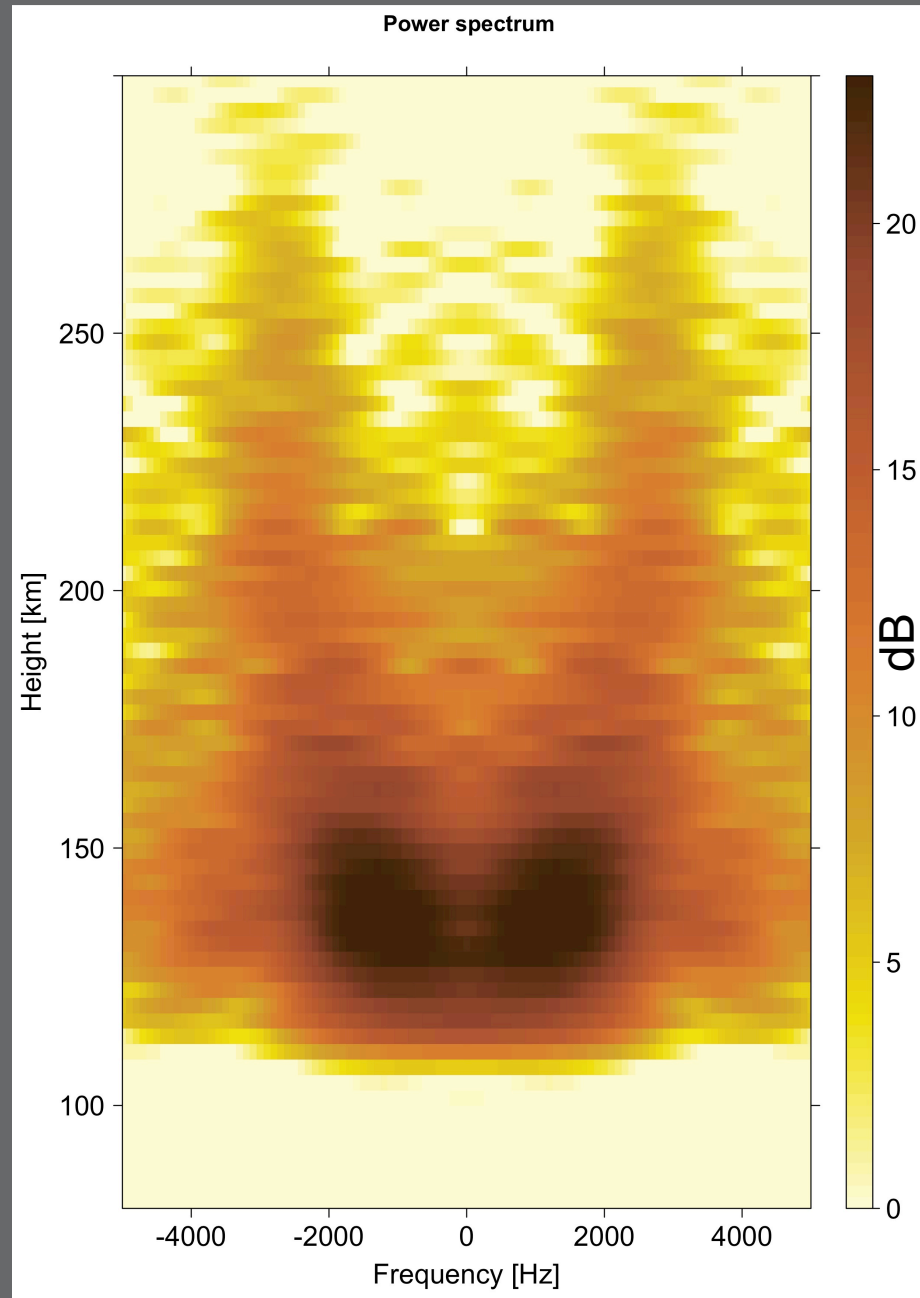
Incoherent scatter radar measurement

- Divide the radar beam into range gates
- Estimate power spectrum of the scattered signal in each gate
- Fit plasma parameters to the observed spectra



Incoherent scatter radar signal



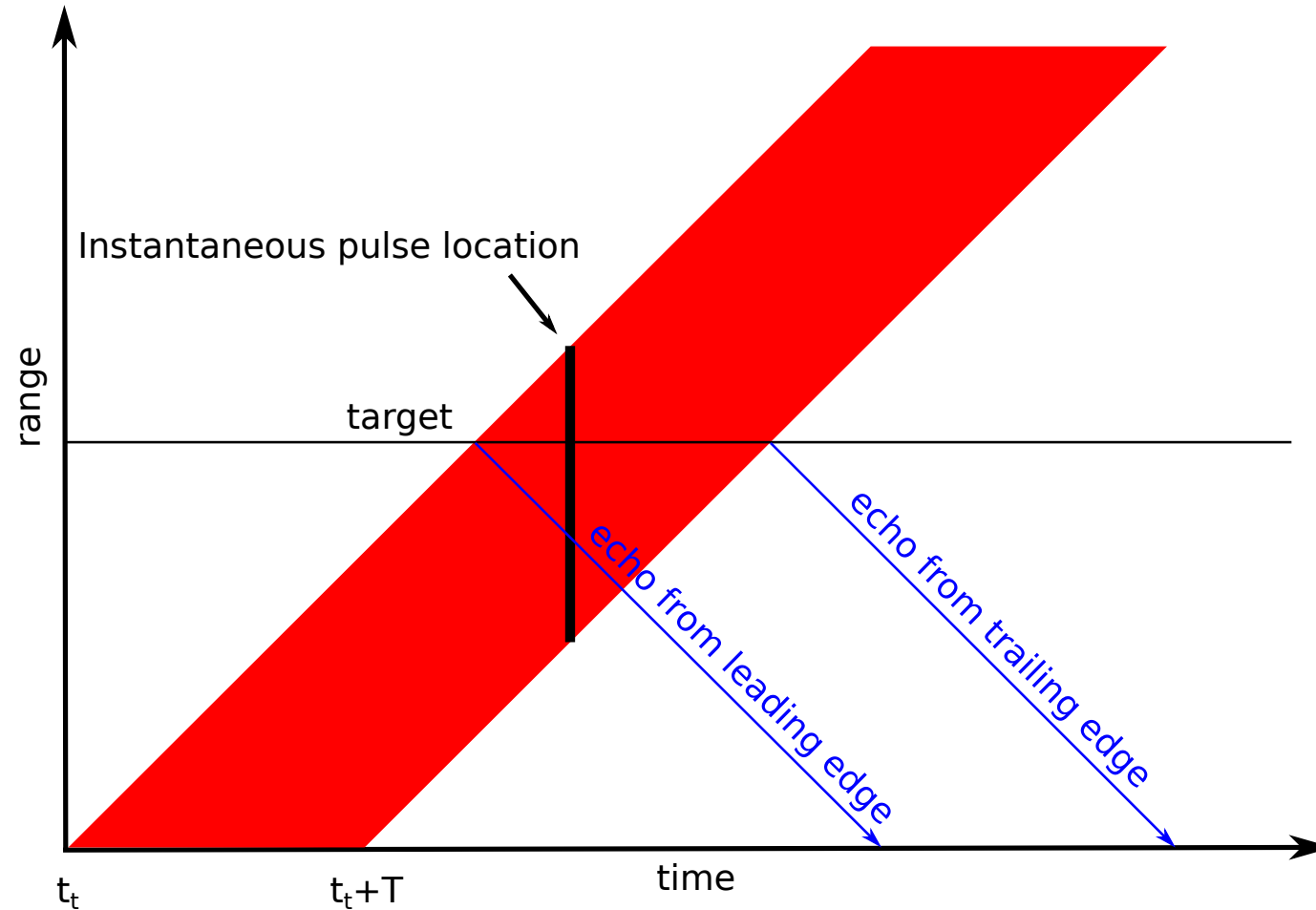


Incoherent scatter spectrum at 224 MHz

- The spectrum is ~ 10 kHz wide
- We need $f_s \geq 10$ kHz
- Signal roundtrip time to 300 km altitude is 2 ms (0.5 kHz)
- The target is overspread, how to properly sample the spectrum?

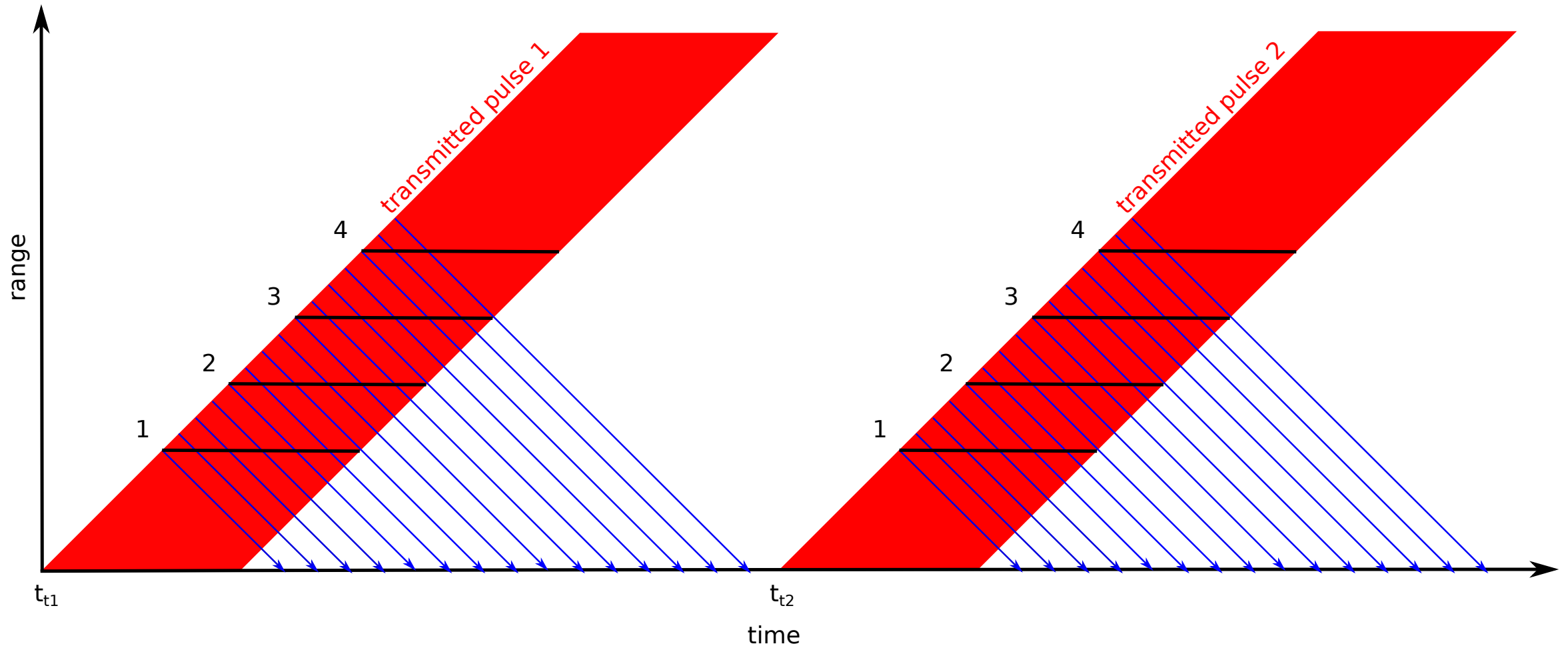


Range-time diagram, pulse length T



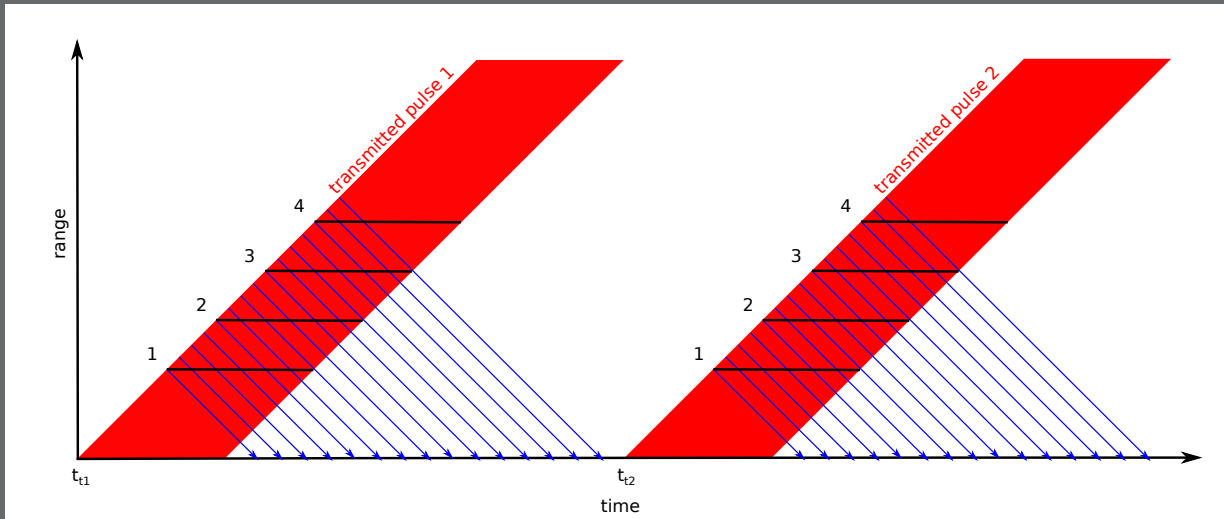


Range-time diagram: multiple long pulses, 4 targets





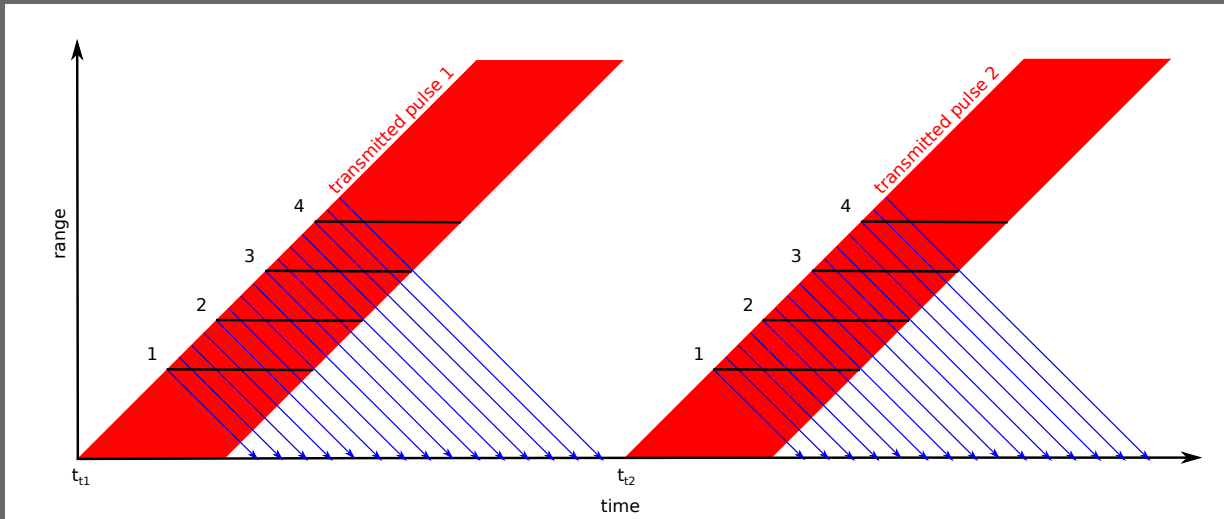
Long pulses



- Enable very high sampling rate
- Each sample has contribution from a wide altitude interval (=several targets)
- We must somehow separate the echoes from different distances
- Phase coding!



Lag profiles and autocorrelation theorem



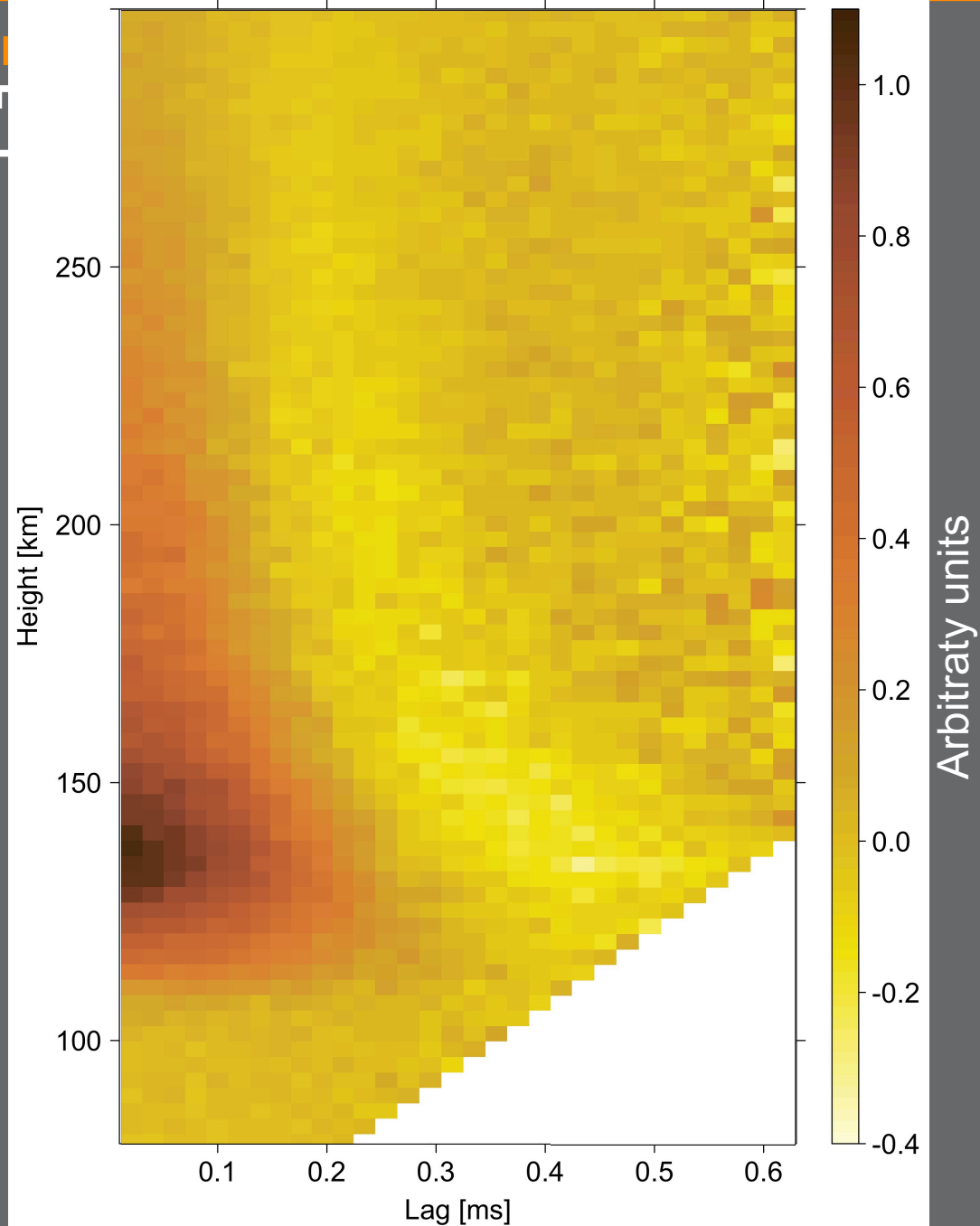
– In the case of incoherent scatter, we cannot decode to resolve the original scattered signal $z(r, t)$

– However, we can resolve the autocorrelation function

$$\mathcal{R}_z(\mathbf{r}, \tau) = \langle z(\mathbf{r}, t) z^*(\mathbf{r}, t - \tau) \rangle$$

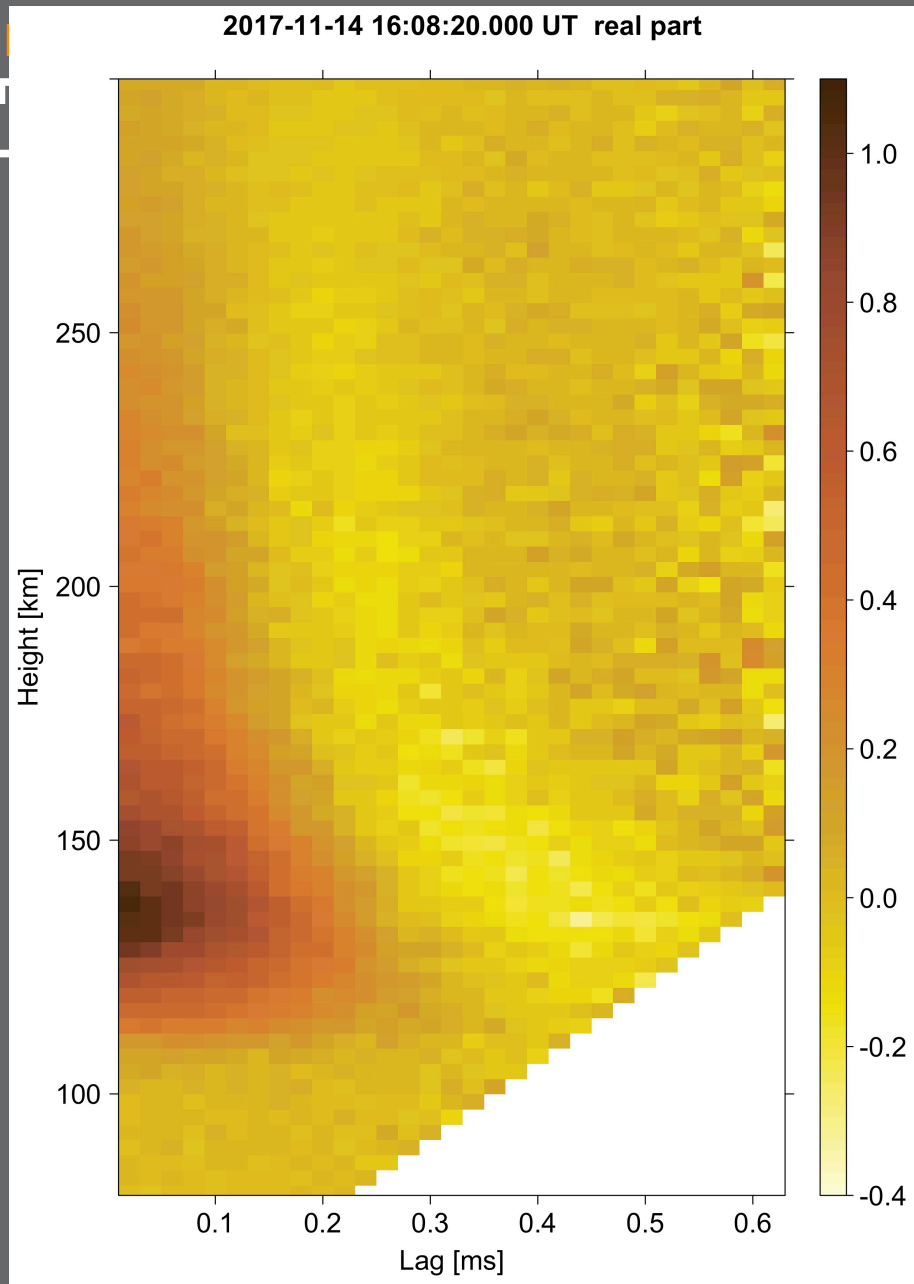
– The power spectrum can be solved with the autocorrelation theorem:

$$S(\mathbf{r}, f) = \mathcal{F}\{\mathcal{R}_z(\mathbf{r}, \tau)\}$$

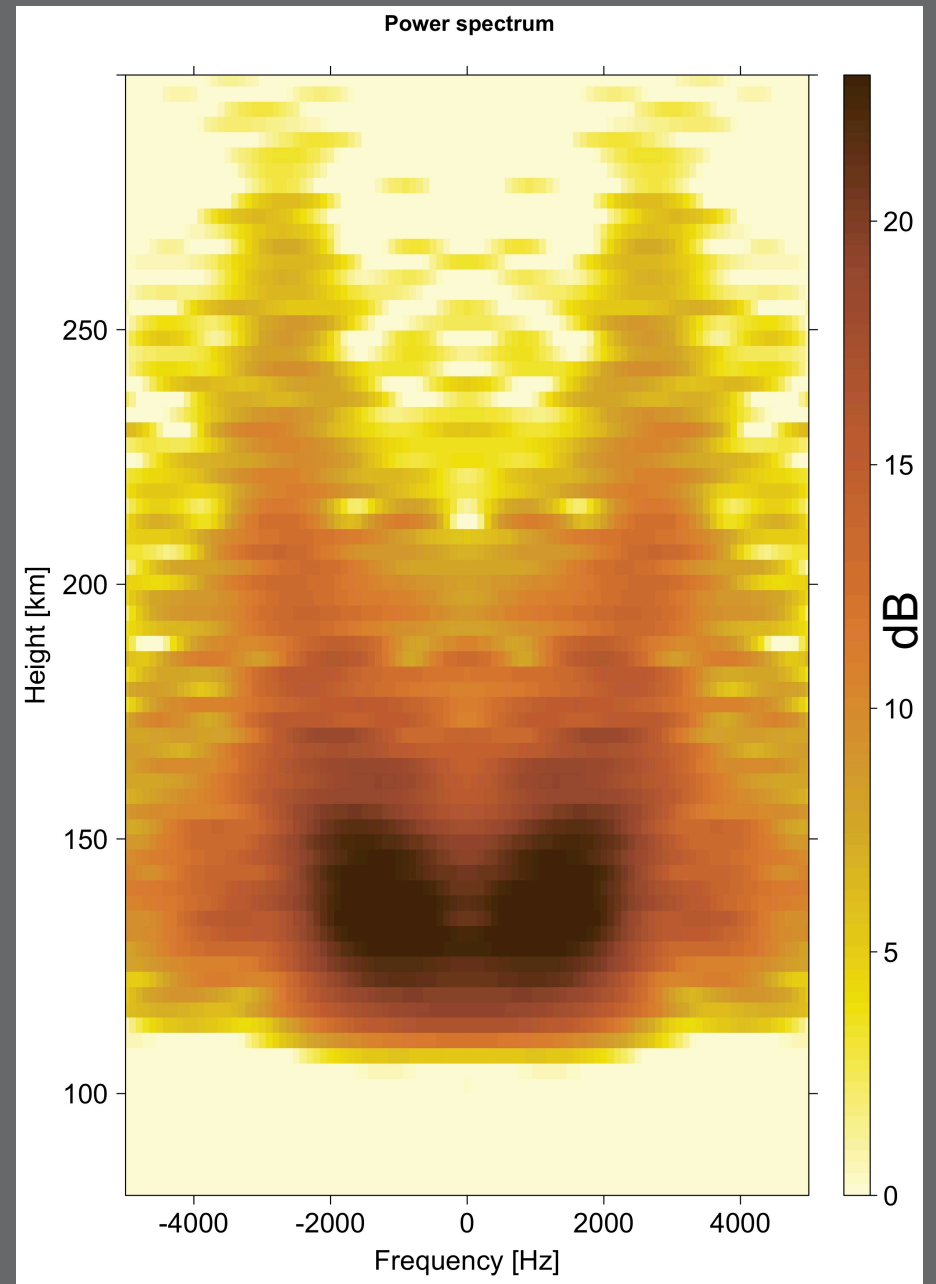


Measuring the autocorrelation function

- Transmit a sequence of long, phase-coded pulses
- Resolve "lag profiles", range profiles of $\mathcal{R}_z(\mathbf{r}, \tau)$ at several different lags τ .

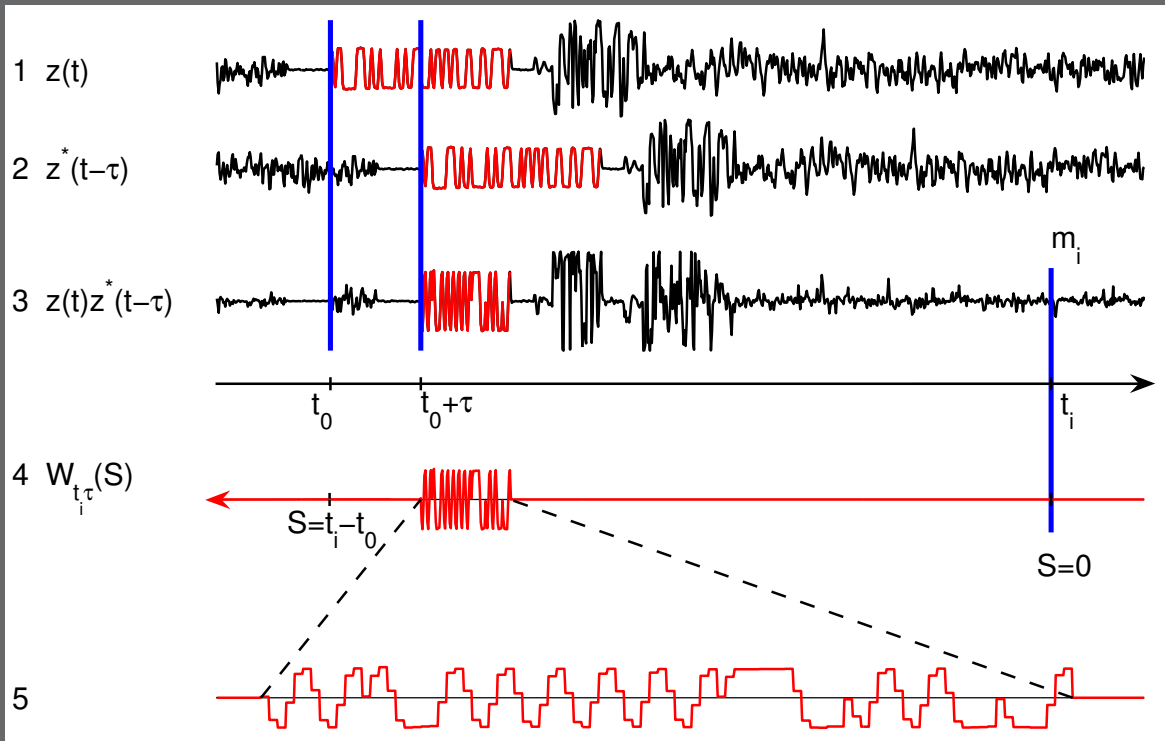


DFT





Pulse compression, incoherent target



- The target changes in time-scales shorter than the pulse length
- Changes in target spectrum are slower
- We can decode the autocorrelation function of the scattered signal instead of the signal itself!
- **Analogy to coherent targets**
 - Echo amplitude \Leftrightarrow lag profile
 - Transmitted waveform \Leftrightarrow Range ambiguity function
- **Lag profile**
$$\mathcal{R}_z(S, \tau) = \langle z(S, t)z^*(S, t - \tau) \rangle$$
- **Range ambiguity function**
$$W(t, S, \tau) = z_e(t - S)z_e^*(t - \tau - S)$$

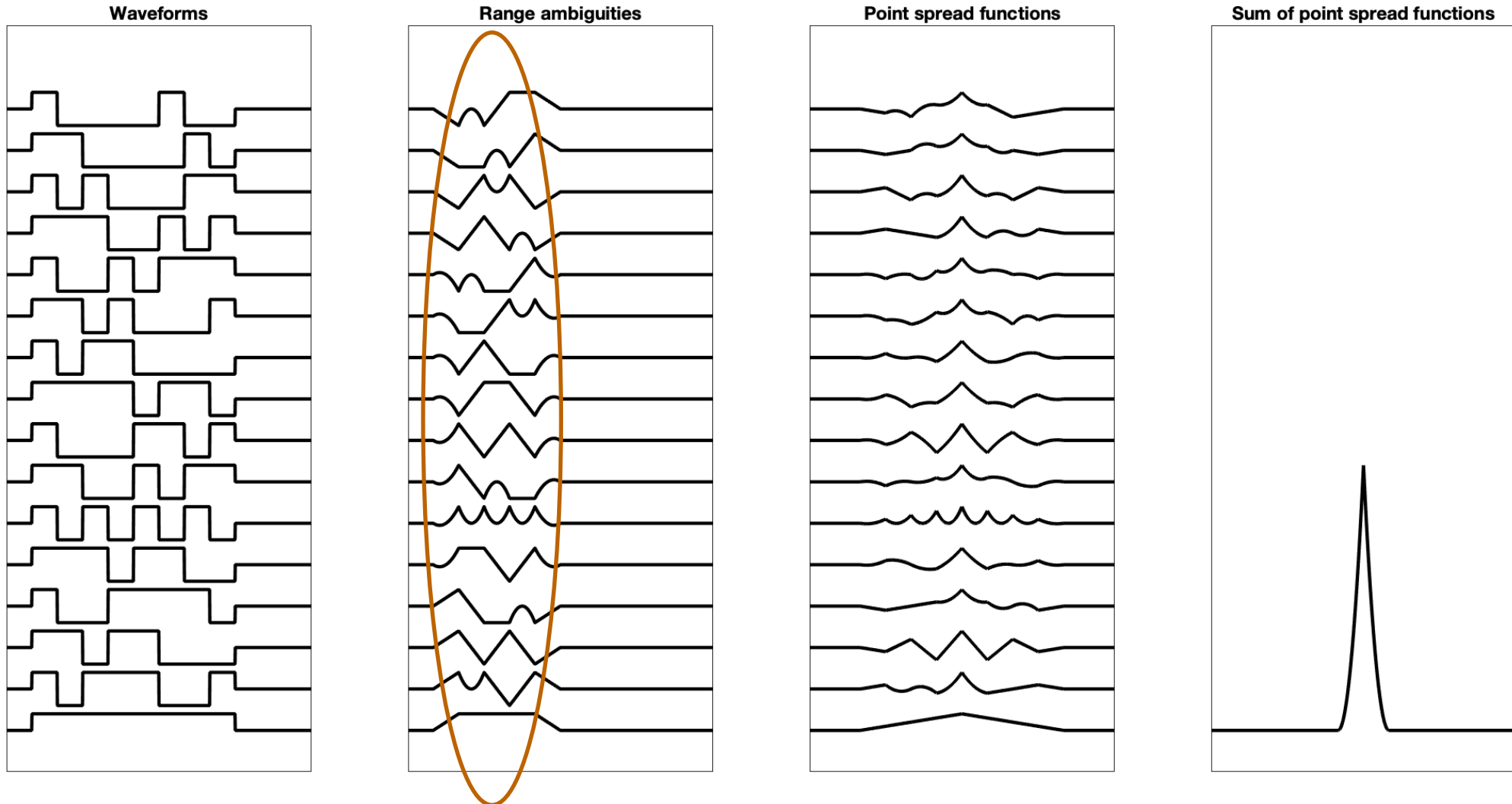


Example: alternating codes

- Sequences of phase-coded pulses
- At each time-lag, the set of range ambiguity functions of the codes forms a complementary code set
- We can decode lag profiles by means of matched filtering!



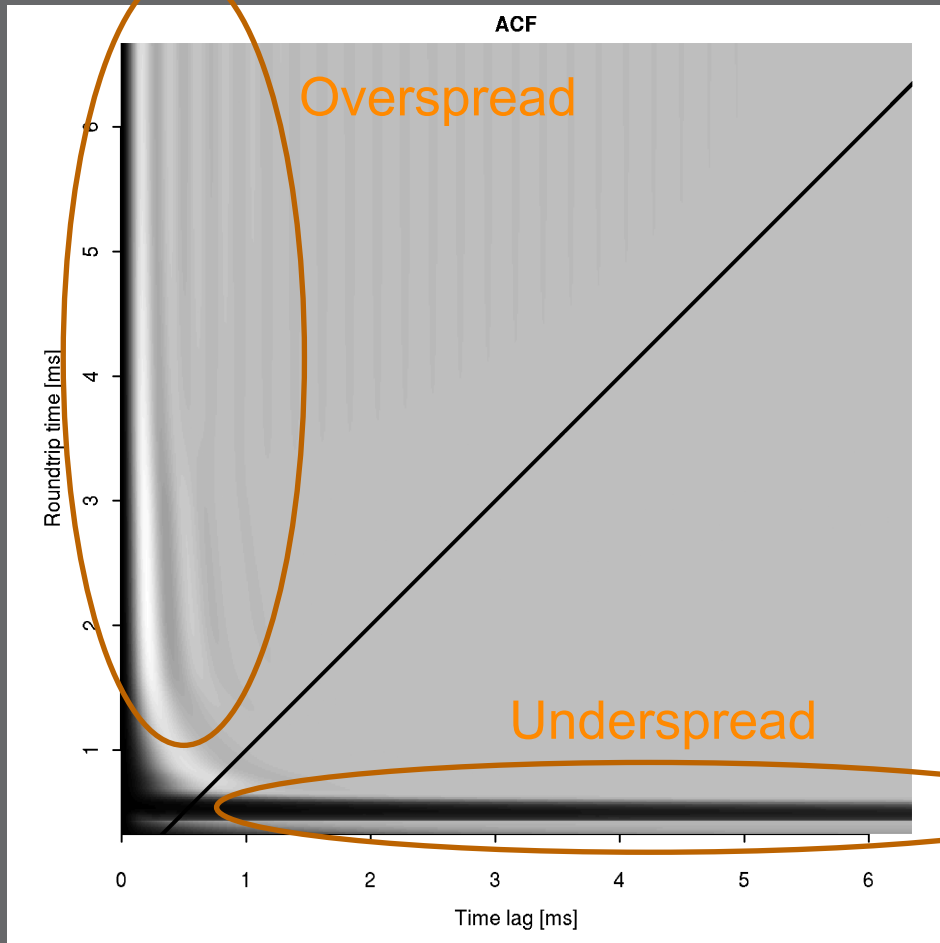
Example: alternating codes



The funny shapes are caused by the receiver impulse response



Underspread vs overspread target



- Signal roundtrip time $S = \frac{2R}{c}$
- Width of the target spectrum Δf
- Underspread target: $\Delta f < \frac{1}{S}$
- The target spectrum can be estimated using echo samples from subsequent transmitted pulses (pulse-to-pulse correlations)
- Overspread target: $\Delta f > \frac{1}{S}$
- We must collect several echo samples from each range per pulse (intra-pulse correlations)
- **The D region is underspread, while the F region is severely overspread. ISR experiment design is not trivial!**

A normalized ISR lag profile matrix



Thanks for your attention!